# Numerical simulations of multiphase and turbulent flows

Daniel Fuster, Cansu Ozhan



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- Subgrid models (particle models)

### Applications

• Investigation of atomization processes: Fuster et al (JFM, 2013)



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Wave turbulence: Deike et al (PRL, 2014)



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 Turbulent and reactive flows in catalytic converters Ozhan et al (CES, 2014)

C. Ozhan et al ()

# **Overview**

#### Numerical development

- Gerris (in particular I develop a new branch of it) and Paris Simulator
  - Tools for turbulence simulations
    - Turbulence models (LES).
    - Special numerical schemes (skew-symmetric formulation)
    - Numerical tools for the analysis of turbulent structures (FFTW for flow field variables and interfaces)
  - Special Adaptive Mesh Refinement features and subgrid models.

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# Numerical schemes for turbulent flow simulations

#### How to handle multiphase flows and turbulence in Gerris?



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# Skew-symmetric formulation [J. Comp. Phys, 2013]

#### Isotropic turbulence



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#### Isotropic turbulence

$$E(k) = \alpha \epsilon^{2/3} k^{-5/3} f_L(kL_{int}) f_{\nu}(kL_{int} \operatorname{Re}_L^{-3/4})$$

$$L_{int} = 0.5L_{box}$$

$$\operatorname{Re}_L = \frac{\sqrt{\int_0^\infty E(k) dk} L_{int}}{\nu} = 375$$

$$k = \int_0^\infty E(k) dk = 0.5,$$
Skew-Symmetric vs. Bell-Cotella-Glaz
$$\int_{\frac{126}{5}}^{0.14} \int_{\frac{126}{5}}^{\frac{323}{5}} \int_{0}^{0} \int_{0}^{0.24} \int_{0}^{\frac{323}{5}} \int_{0}^{0} \int_{0}^{0} \int_{0}^{0} \int_{0}^{14} \int_{0}^{\frac{323}{5}} \int_{0}^{0} \int_{0}^{0} \int_{0}^{14} \int_{0}^{0} \int_{0}^{2} \int_{0}^{0} \int_{0}^{$$



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Efficient AMR criteria for vortical structures

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We significantly reduce the error of high order statistics



Efficient AMR criteria for vortical structures

#### Effect of multiple phases (same Reynolds in both phases)



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   Work in progress

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- DNS are expensive, how to reduce the computational effort?
  - Adaptive Mesh Refinement (AMR)
  - Subgrid models (Particle module)

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We are interested in developing numerical tools for the simulation of turbulent flows.

In particular this work is motivated by the flow simulation inside a catalytic converter system:



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In particular this work is motivated by the flow simulation inside a catalytic converter system:



Adaptive Mesh Refinement (AMR) help us to save a significant amount of computational time!

### Problematic:

 DNS is not always possible because the smallest scale on the problem can be really small

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- What we want is to get as close as possible to the real solution trying to optimize the grid distribution

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#### Test cases

In order to measure the efficiency of AMR techniques we need:

Simplified test cases with analytical solution

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#### Test cases

In order to measure the efficiency of AMR techniques we need:

- Simplified test cases with analytical solution
- We want to measure the global and local efficiency of the method

We need to chose:

- A method to estimate the error
- A norm to adapt the grid:

AMR criteria  $\rightarrow \text{Error} \times \Delta x^n$ 

#### Error indicators

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- Gradient (velocity, tracer)
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- Helicity norm (3D)

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- Conservative variables (momentum, energy...)
- Primitive variables (velocity, pressure...)
- Variables related to turbulent flows (vorticity, helicity...)

## A residual based method

We try to obtain a measure of the discretization error when solving a given equation

$$M\frac{Y^{n+1} - Y^n}{\Delta t} = F_{conv}(Y^{n+1/2}) + F_{diff}(Y^{n+1/2}) + S$$
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In advection dominated flows (steady-state)

$$\boldsymbol{F}_{conv}(\boldsymbol{Y}) = \boldsymbol{S} \tag{2}$$

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- and reaction limit



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For each cell the mechanism controlling the error can be different depending on the local Reynolds number, etc....

This criteria also reduces the error propagation (we reduce the error of the RHS of the equation)

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The optimal choice is problem dependent

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Error estimation for the transport equation: Propagation error only controls in regions where the error is small Steady problem



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Error estimation for the transport equation: Propagation error only controls in regions where the error is small Steady problem



Transient  $T = T_{steady} + T(t)e^{i\omega t}$ 













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Three test cases related to our problem of interest:





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#### Test cases

Dissipation of the Lamb-Oseen vortex
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- Dissipation of the Lamb-Oseen vortex
- Linear growth of random noise in a shear layer

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- Isotropic turbulence test case

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Image: A matrix

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## Lamb-Oseen vortex



$$u_{\theta} = \frac{\Gamma}{2 \pi r} \left[ 1 - exp\left( -\frac{r^2}{4 \nu t} \right) \right].$$

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Local efficiency: Estimated error vs. Real error



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$$U = \Delta Uerf\left(y/\delta_c\right)$$



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## Isotropic turbulence

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$$k = \int_0^\infty E(k) dk = 0.5,$$

The characteristic lengthscale changes in time



Efficient AMR criteria for vortical structures





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Perspectives: To investigate the process of bubble breakup in forced isotropic turbulence



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$$\sigma_V = \frac{1}{\dot{m}} \int_A |U_i - U_e| \, \delta \dot{m}$$

Re = 20000



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Re = 60000



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Re = 80000









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- $L_{\infty}$  performs betters than  $L_1$  norm for low resolved simulations when looking at high order statistics... but it is not always easy to control!
- AMR allow us to reproduce the flow distribution inside a catalytic converter at much lower resolutions

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