

What is the liquid jet atomization problem? Will Gerris help us solve it?

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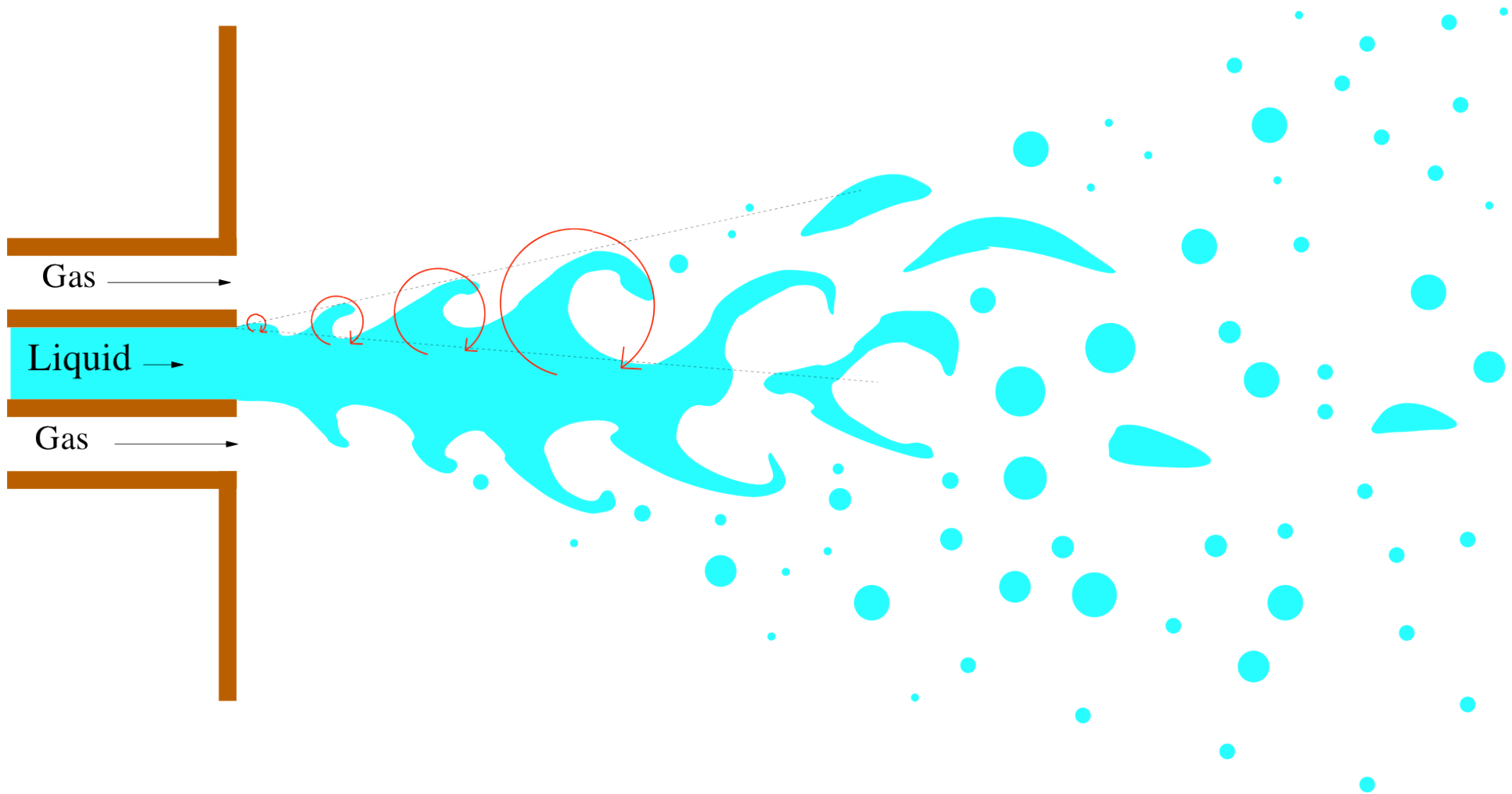
<http://www.imm.jussieu.fr/~zaleski>

Collaborators past and present on atomization.

Jie Li (BPI, Cambridge), Phil Yecko (Montclair, NJ), Thomas Boeck (Ilmenau), Jose-Maria Fullana (d'Alembert), Ruben Scardovelli (Bologna), Stéphane Popinet (d'Alembert), Pascal Ray (d'Alembert), Luis Lemoyne (Nevers), Gaurav Tomar (Bangalore), Daniel Fuster (d'Alembert), Anne Bagué (ONERA), Jérôme Hoepffner (d'Alembert), Ralph Blumenthal (TUM), Annagrazia Orrazo (Naples).

Current Student

Gilou Agbaglah

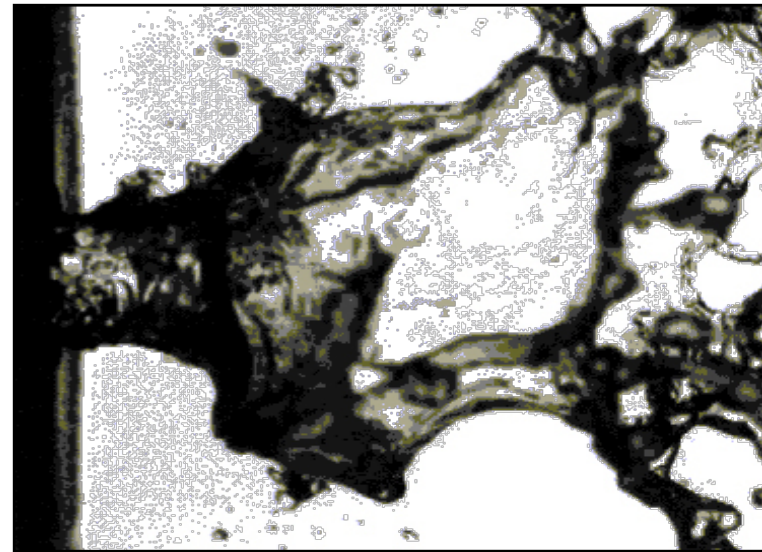
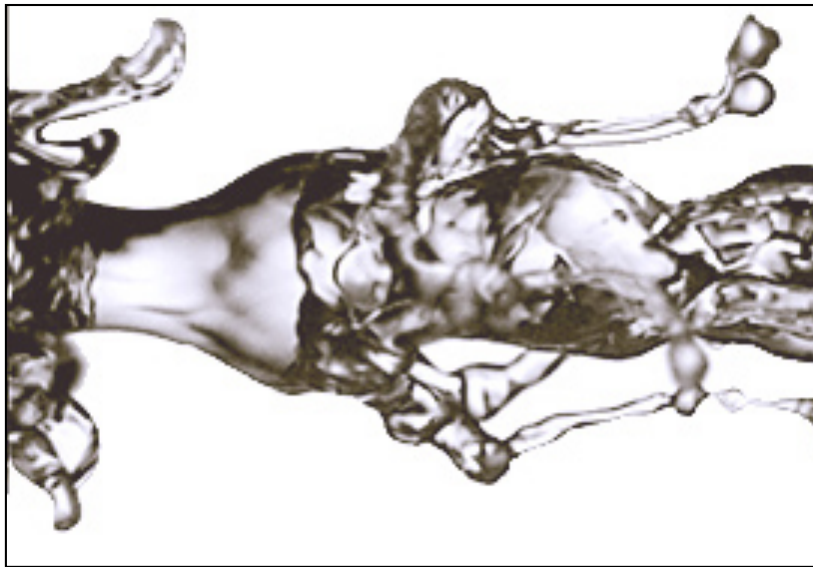


coflowing jet atomization (rocket engines, Formula 1 racing cars)

Interpretation 1: the simulation of liquid jet atomisation requires enormous resources. It is thus a grand challenge similar to the DNS of turbulent flow. The one with the most robust code and the biggest computer wins.

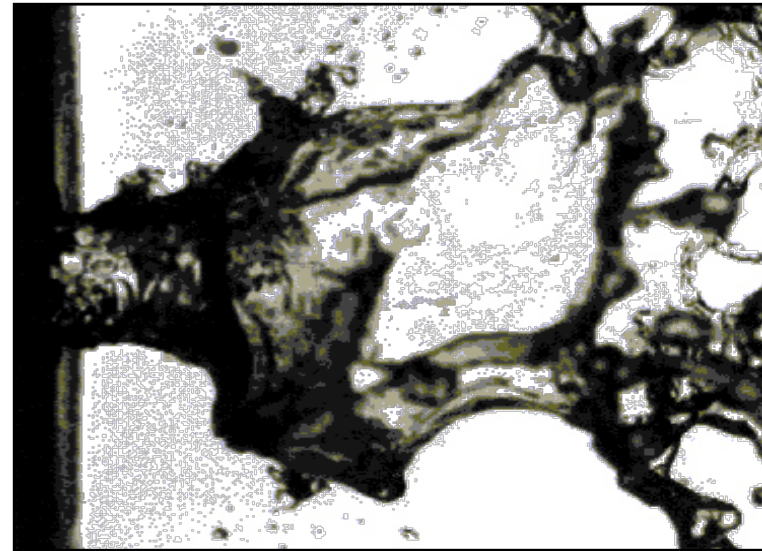
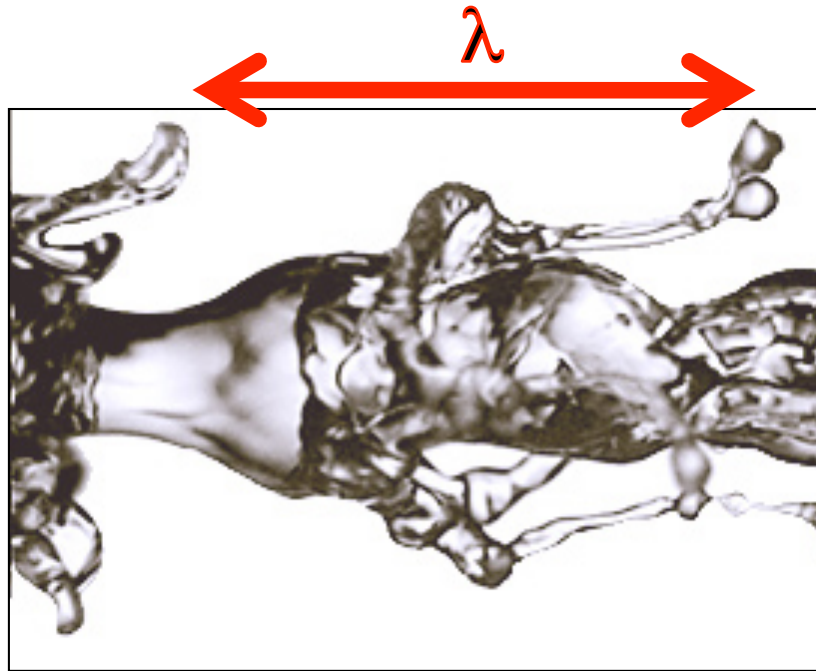
Interpretation 2: A series of mechanisms are involved in the breakup of the jet and generation of the droplets. Explaining these mechanisms and making quantitative predictions solves the problem.

Atomization of co-axial jets : experiments with **air/water** jets

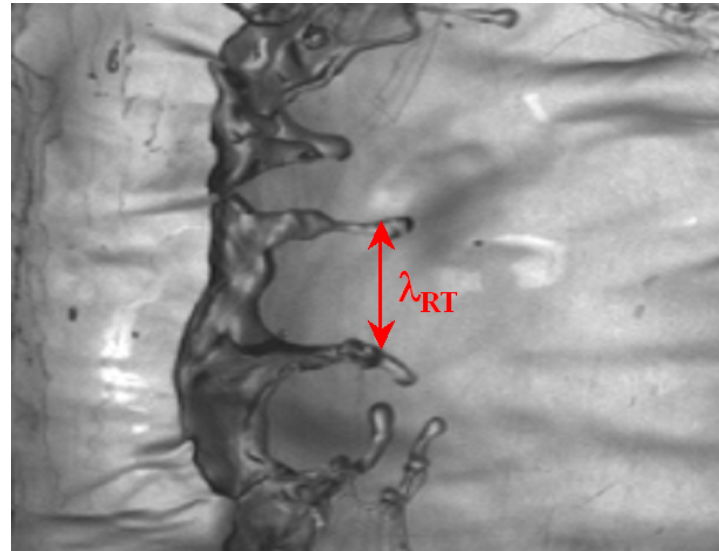
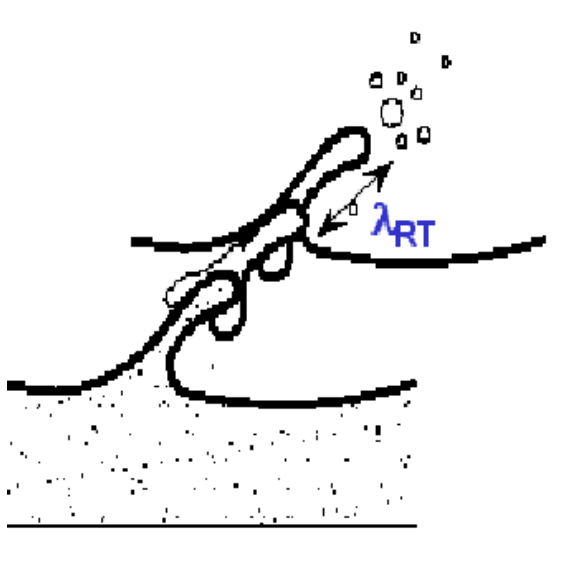


Lasheras, Hopfinger, Villermaux, Raynal, Cartellier ...,
(San Diego, Grenoble and Marseille)

Problem 1: predict the transverse wavelength λ or the frequency f



an atomizing sheet seen from
above:



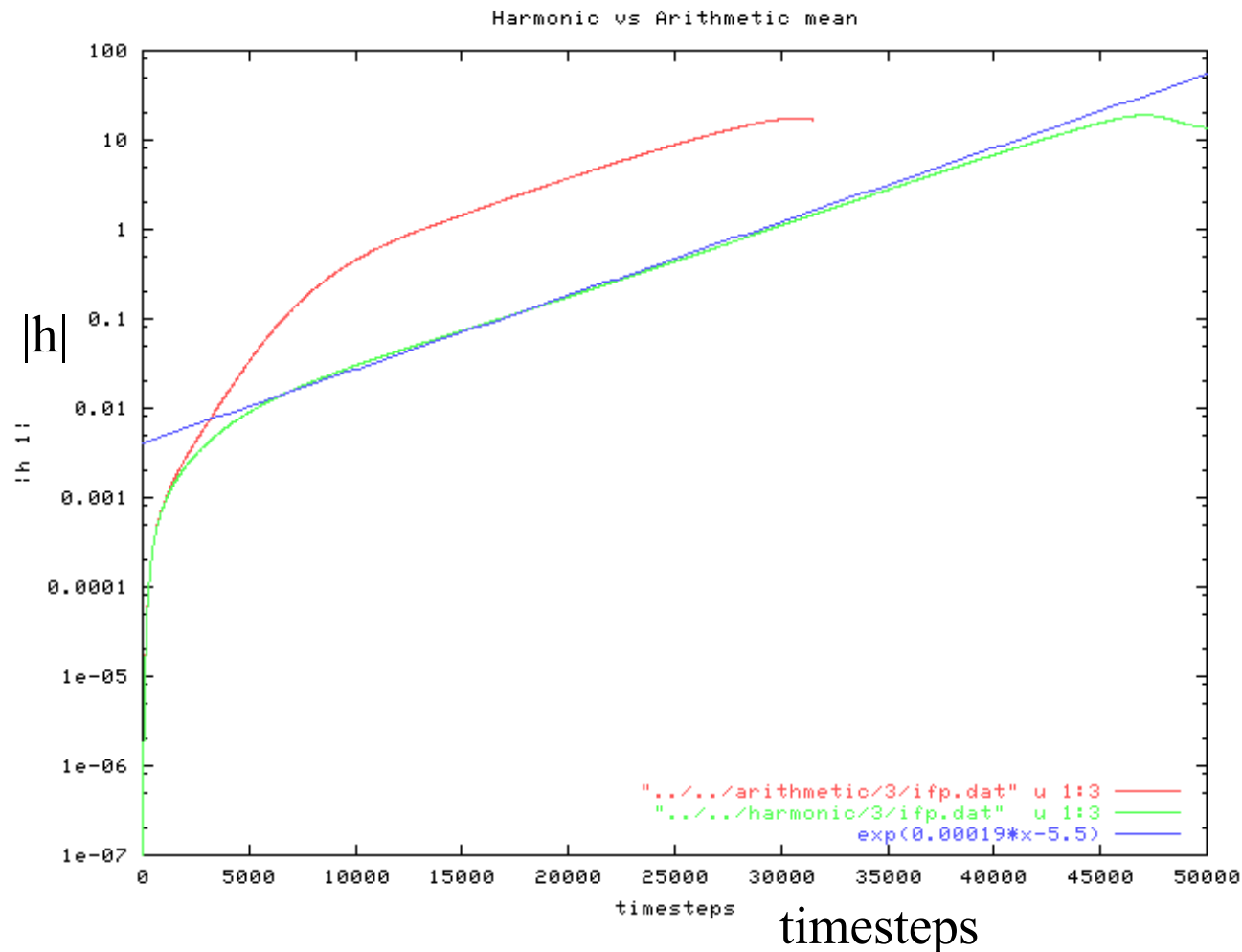
Photograph: Cartellier and Matas

Problem 2 : predict λ_{RT} . λ_{RT} refers to the theory of Cartellier and Hopfinger but in fact several “Rayleigh-Taylor” mechanisms have been suggested in the literature.

Kelvin-Helmholtz instability

perform simulation of unstable shear flow

Full DNS and Orr-Sommerfeld agree



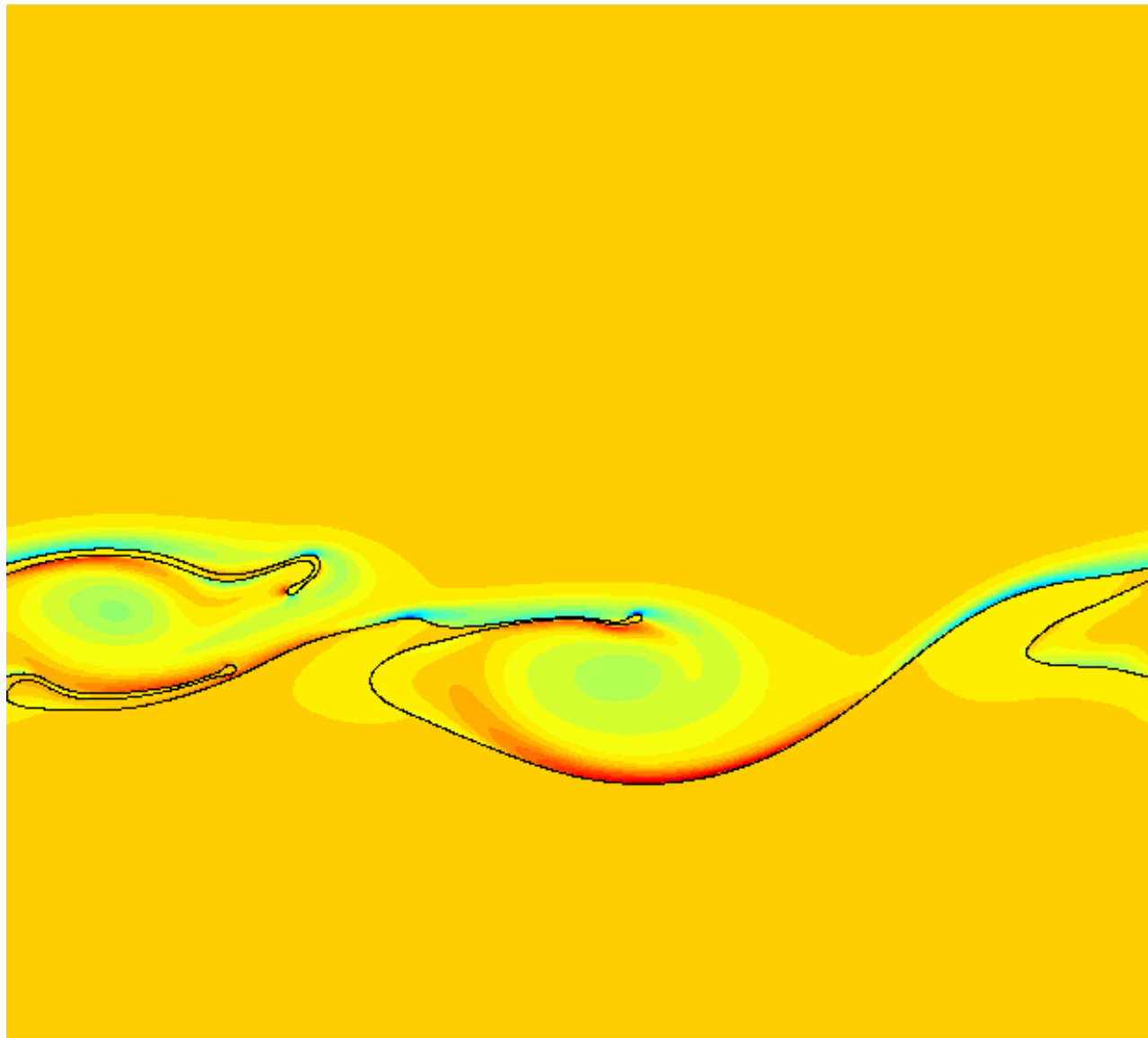
Boeck & Zaleski PoF 2005, Boeck, Li, Lopez-Pages, Yecko & Zaleski TCFD 2007,
Bagué, Fuster, Popinet, Scardovelli and Zaleski, PoF 2010.

Case	m	r	δ_l/L_l	δ_g/L_g	Re_l	Re_g	We_l	We_g
<i>A</i>	0.1	1	1/6	1/6	200	2000	∞	∞
<i>B</i>	0.1	1	1/6	1/6	200	2000	10	10
<i>C</i>	0.99	0.1	1/6	1/6	19800	2000	∞	∞
<i>D</i>	0.99	0.1	1/6	1/6	19800	2000	100	10

Error level in percentage points :

code	GERRIS					SURFER			
case	16	32	64	128	256	32	64	128	256
<i>A</i>	-	21.33	10.74	3.50	1.5	-	22.87	10.47	5.82
<i>B</i>	-	7.30	1.28	0.48	1.04	-	29.43	20.47	13.94
<i>C</i>	3.00	1.17	0.24	0.14	0.09	33.21	16.72	8.63	4.32
<i>D</i>	3.98	1.39	0.76	0.07	0.54	33.49	16.1	8.67	6.19

Gerris is much more accurate than Surfer but the error stops decreasing for 256 !



$Re_g = 4000$,
 $We_g = 4000$
 $r = 10$
 $m = 0.025$
vorticity.

Diesel
jet
conditions

Bagué
Popinet
Yarlagadda

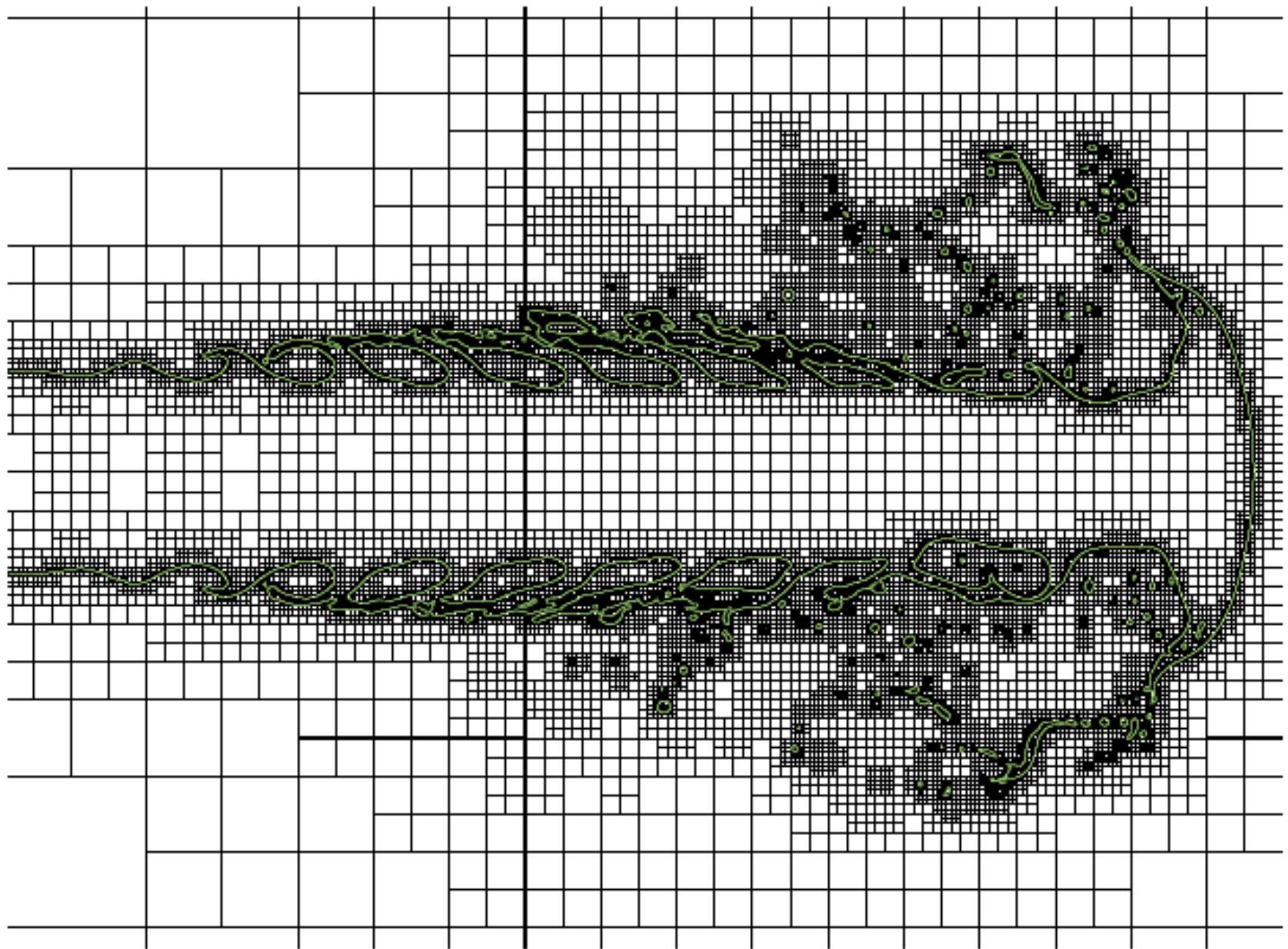
$$\rho_l / \rho_g = 28$$

$$We_l = 11600$$

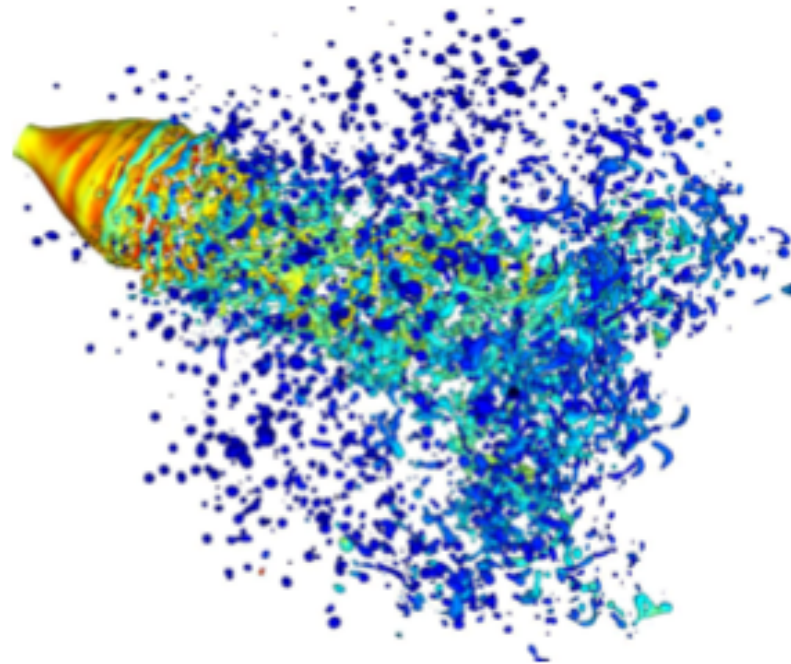
$$Re_l = 5800$$

It is a
Gerris
example
now !

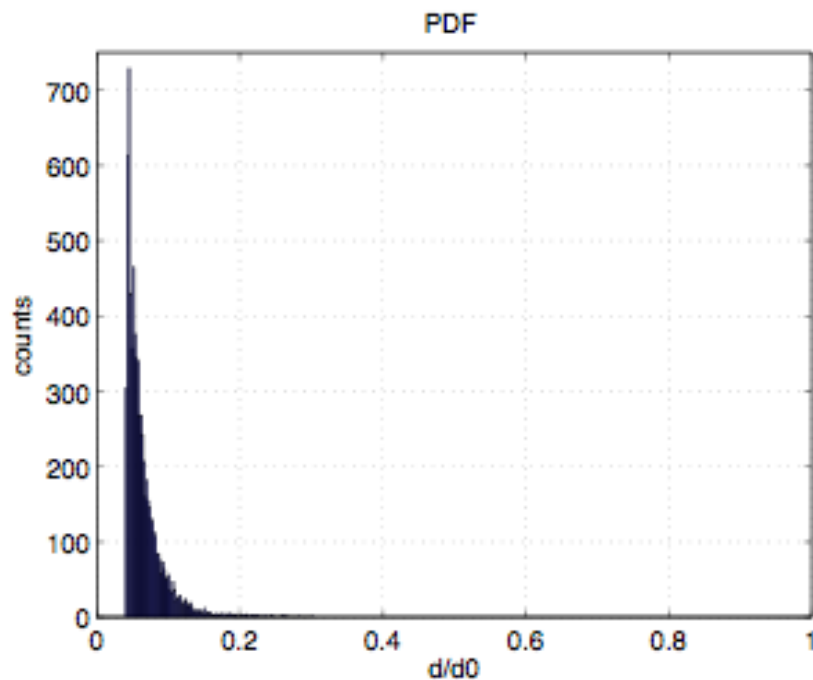




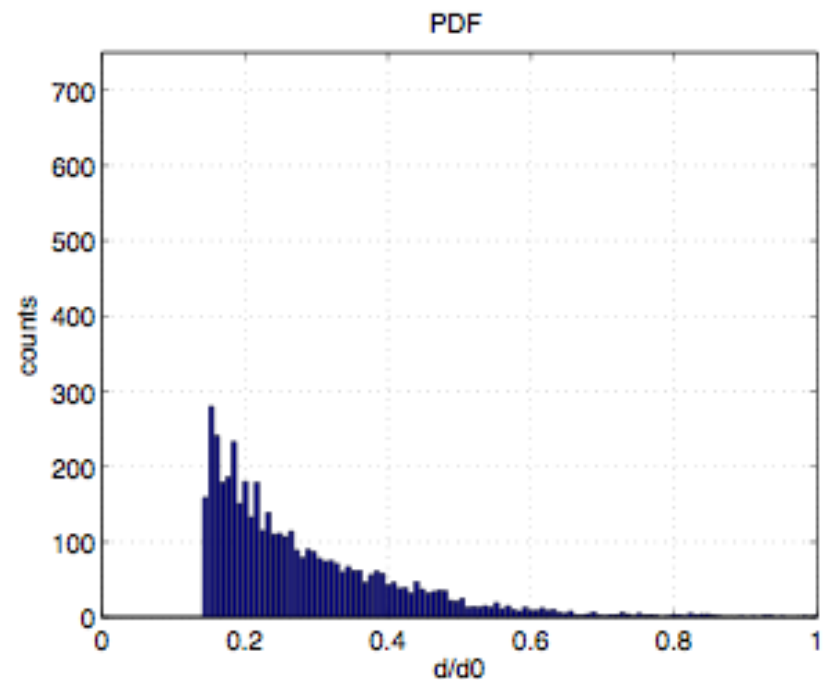
More realistic engineering: 3D conical jet



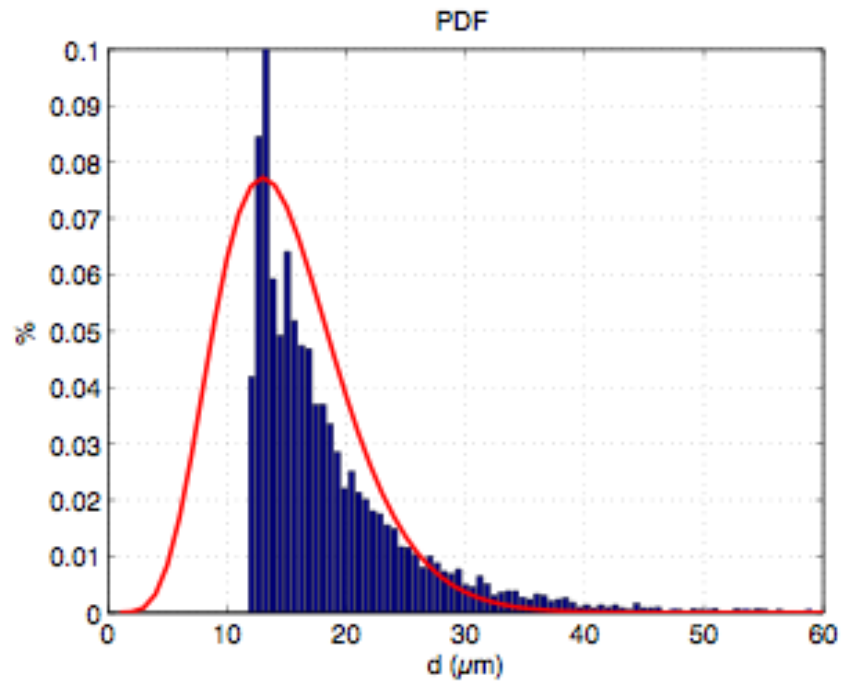
Distribution of droplet sizes (PDF) depends on grid size ! ☹



$\Delta x = 9$ microns

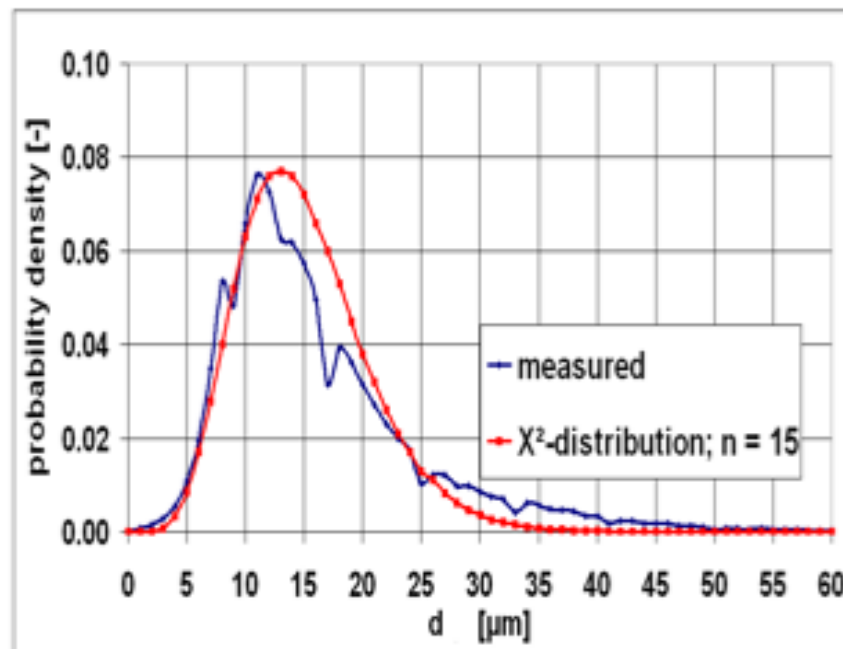


$\Delta x = 28$ microns



But agrees with experiment
at finest resolution ☺

$$dx = 9 \text{ microns}$$



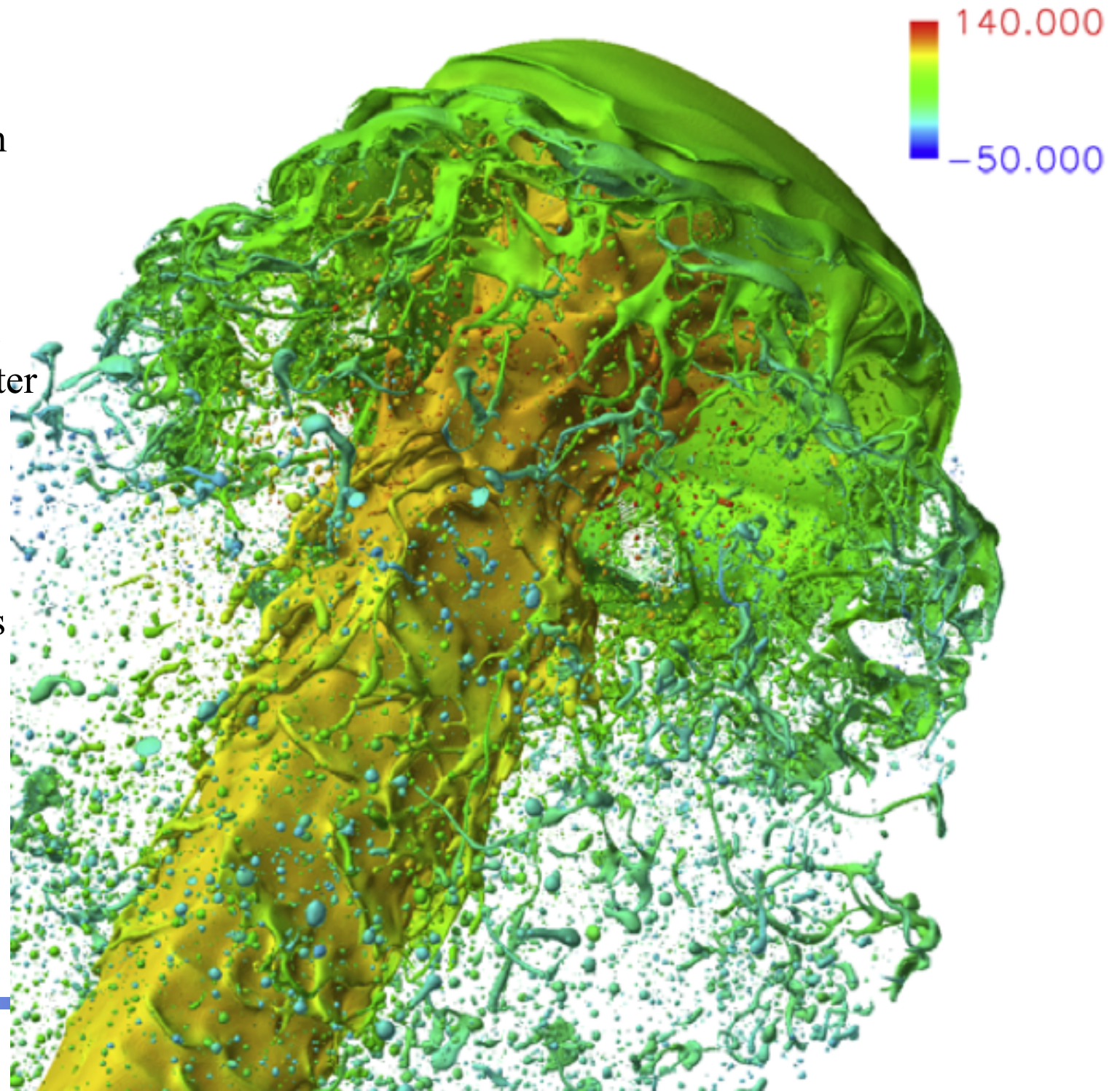
experiment

Clearly, we are not
world champions in
terms of hardware
usage

Shinjo and Uemura
JAXA supercomputer
 $\Delta x = 350$ nm

5760 cores
for 410 hours
6 billion grid points
(uniform)

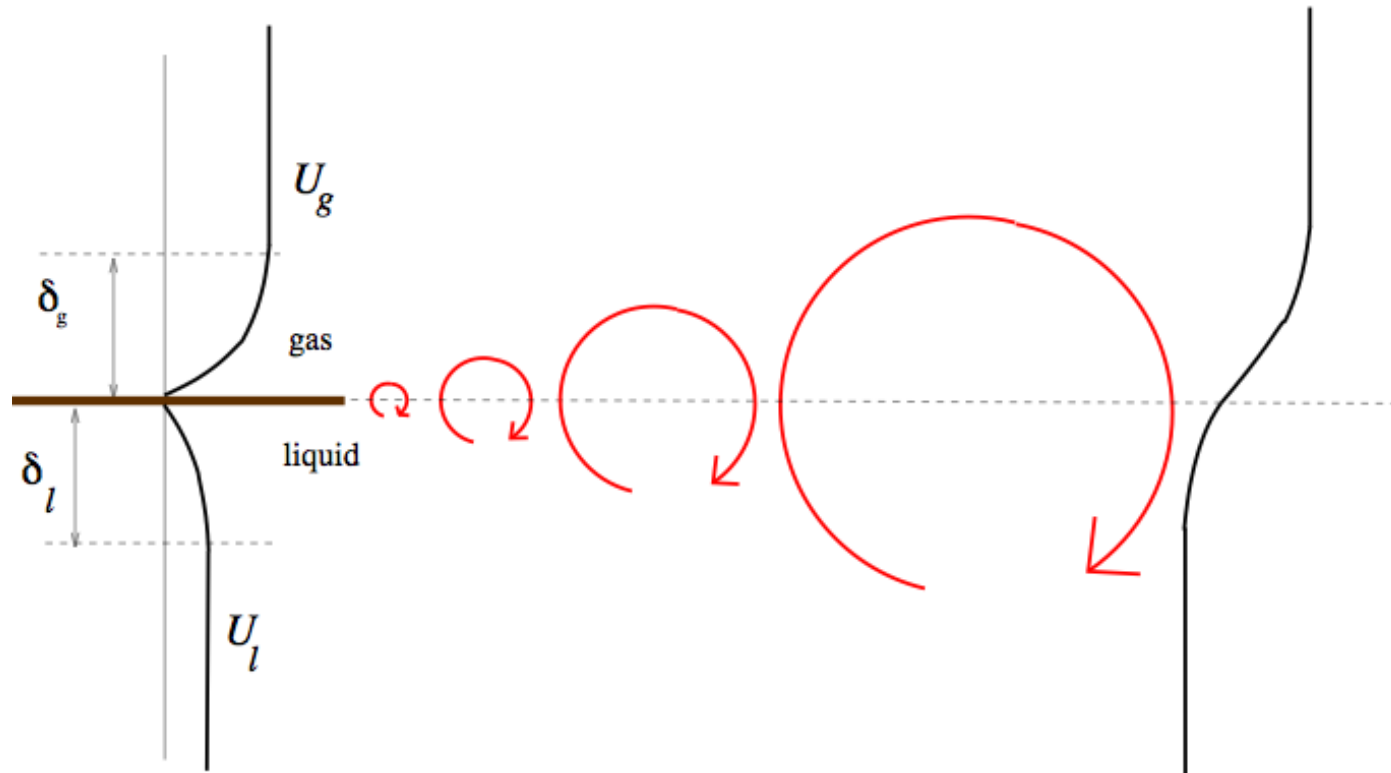
$We = 14000$
 $Re = 1470$
 $U = 100$ m/s



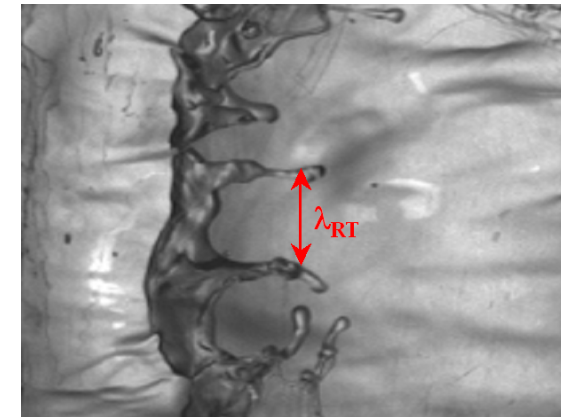
- Need for better parallelism. (although we get 6 billion grid points equivalent with 40 cores ...)
- Need for **multiscale treatment** : combine DNS with some type of subgrid modelling, for certain regions and certain physics, such as droplets in dilute regions (far from the core).

Interpretation 2: physical analysis of the transverse wavelength.

Analyze the flow as a spatially-developing mixing layer



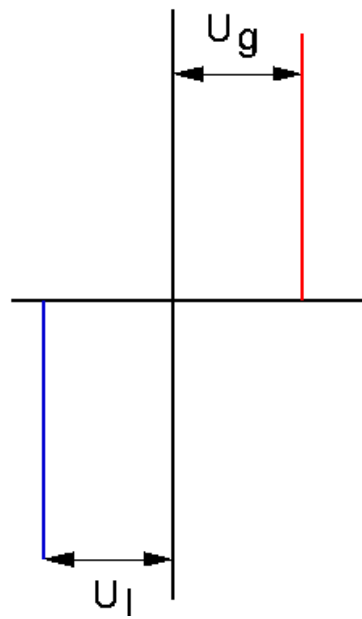
Fully spatial 2D DNS to simulate setup of Grenoble's planar sheet experiment. Large-scale structures are 2D.



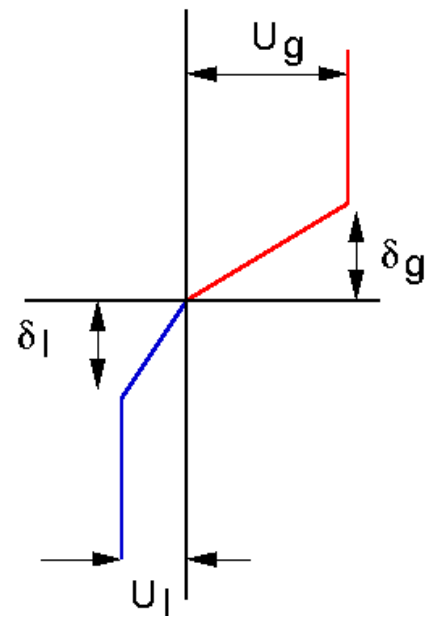
A mechanism of Atomization : the Kelvin-Helmholtz Instability

Linear stability theory of the Kelvin-Helmholtz instability:

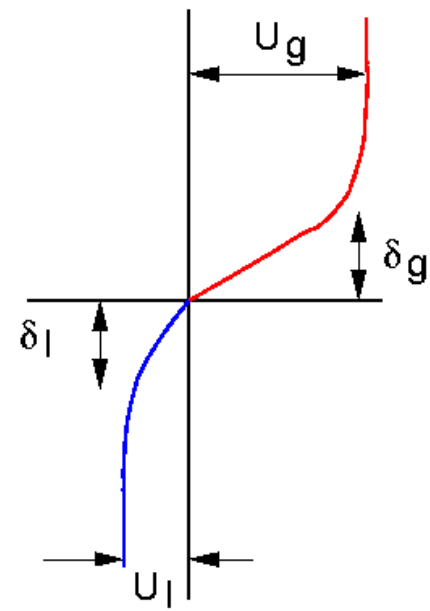
- (a) **Potential flow** (except at interface), Inviscid, Piecewise linear profiles (Marmottant, Raynal, Villermaux, Cartellier, Matas, others ...)
- (b) **Viscous**, Error-function profiles (Yecko, Fullana, Boeck, Zaleski, Gordillo, Perez-Saborid, Ganan-Calvo, Spelt, Valluri, O' Naraigh...)



19



20



21 ...

INVISCID LINEAR STABILITY PROBLEM

Nondimensional form based on gas layer velocity and thickness.

$$\Psi_{l,g} = \Phi_{l,g}(y) \exp(i\alpha(x - ct)), u = \partial_y \Psi, v = -\partial_x \Psi$$

$$(U_{l,g} - c)(D^2 - \alpha^2)\Phi_{l,g} - D^2 U_{l,g} \Phi_{l,g} = 0$$

boundary conditions on interface(s)

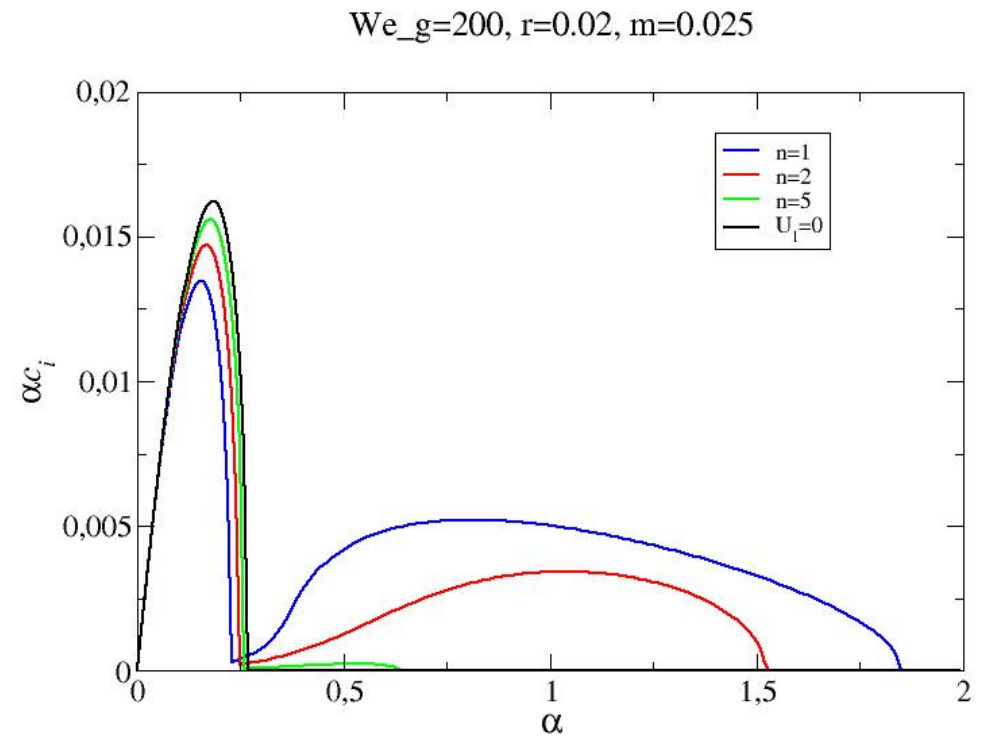
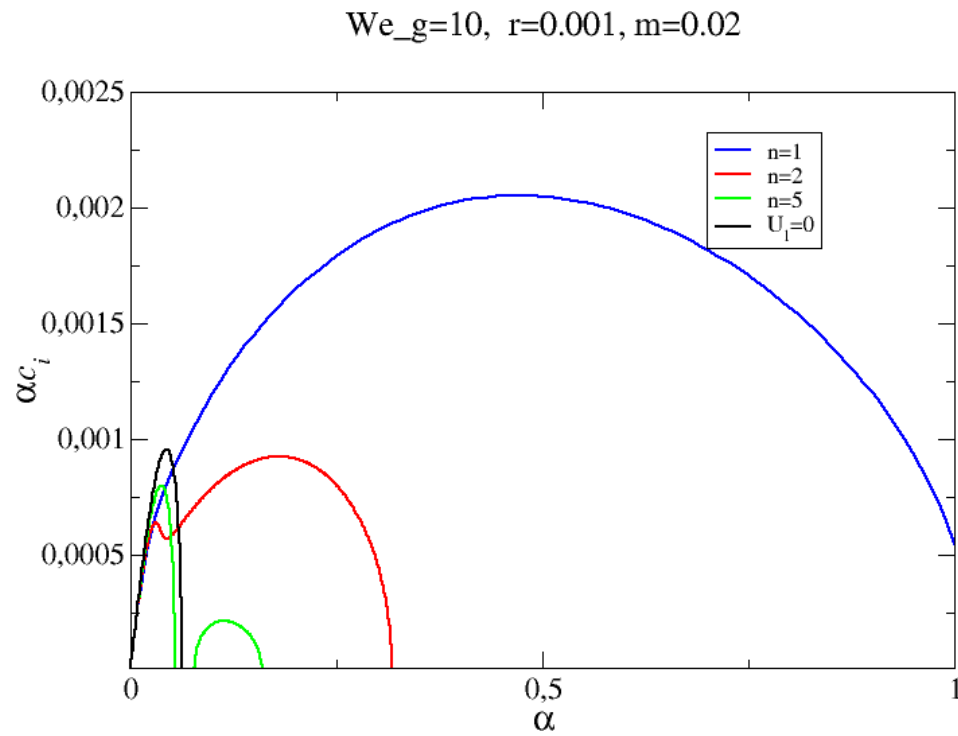
$$\Phi_l = \Phi_g \quad \text{vertical velocity continuous}$$

$$-\frac{\alpha^2}{cWe_g} \Phi_g = -\frac{1}{r} (cD\Phi_l + \Phi_l DU_l) + cD\Phi_g + \Phi_g DU_g \quad \text{P cont.}$$

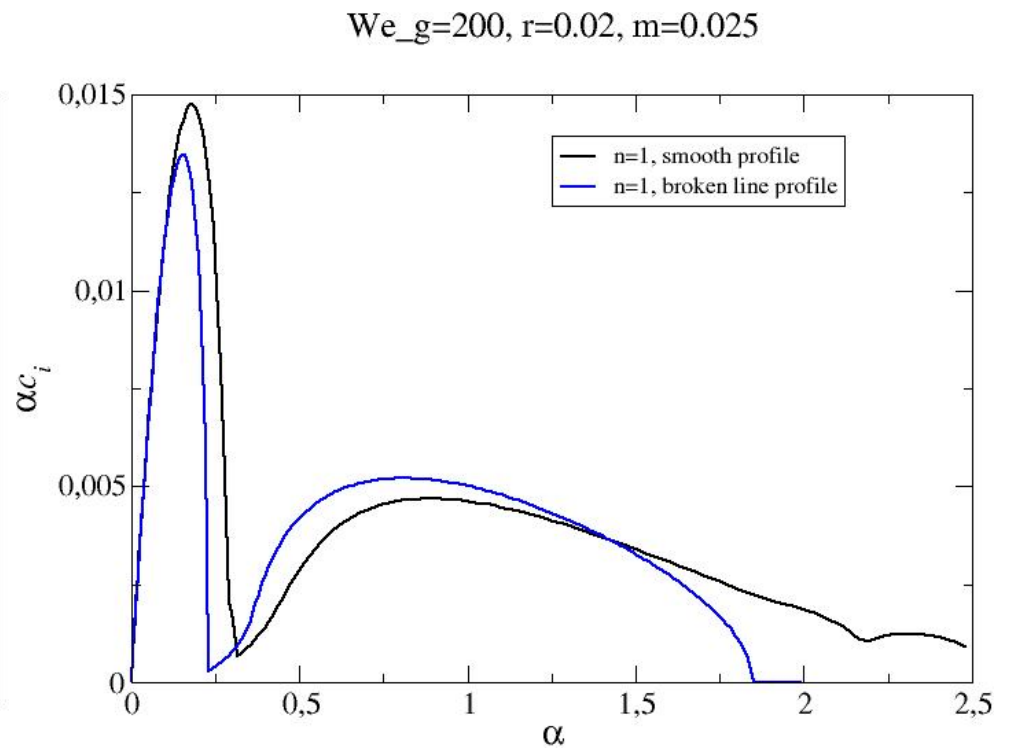
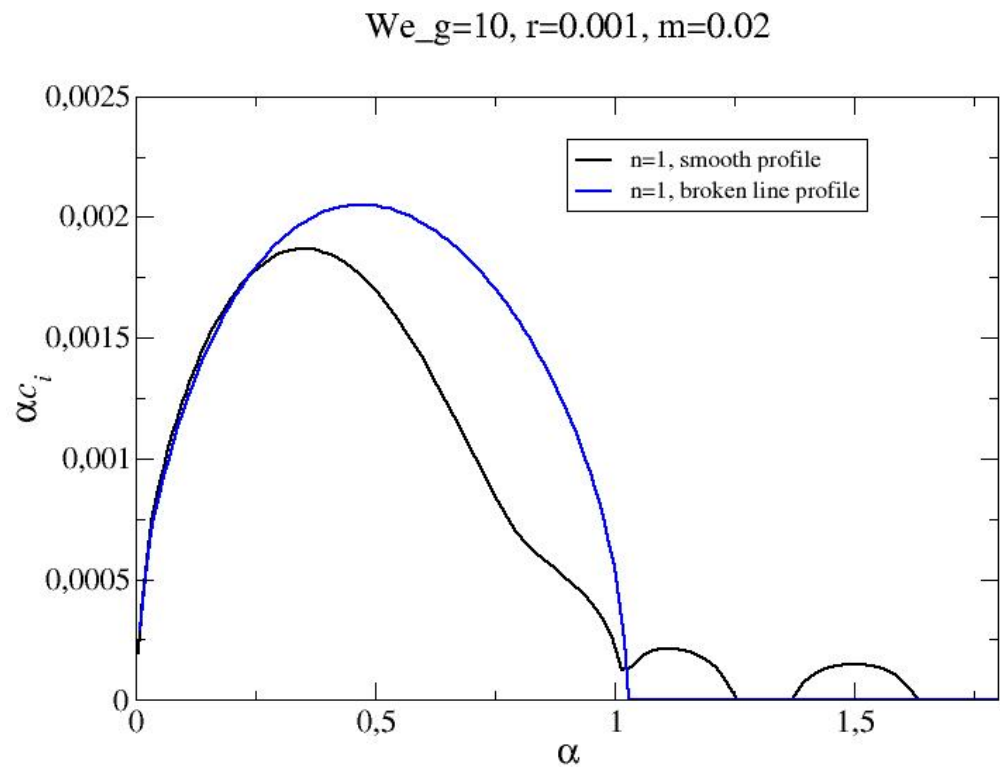
Analytical solution when U linear function of y; dispersion relation then 4th order polynomial for the broken line profiles in liquid and gas phase.

General profile: numerical solution with collocation method based on expansion in Chebyshev polynomials in both (finite) layers.

Broken line profile



Continuous profile



Viscous linear stability problem

Nondimensional form based on gas layer velocity and thickness.

$$\Psi_{l,g} = \Phi_{l,g}(y) \exp(i\alpha(x - ct)), \quad u = \partial_y \Psi, \quad v = -\partial_x \Psi$$

$$(U_g - c)(D^2 - \alpha^2)\Phi_g - D^2 U_g \Phi_g = \frac{1}{i\alpha \text{Re}_g} (D^2 - \alpha^2)^2 \Phi_g$$
$$(U_l - c)(D^2 - \alpha^2)\Phi_l - D^2 U_l \Phi_l = \frac{r}{m} \frac{1}{i\alpha \text{Re}_g} (D^2 - \alpha^2)^2 \Phi_l$$

boundary conditions on interface(s)

$$\Phi_l = \Phi_g$$

vertical velocity continuous

$$D\Phi_l + DU_l \frac{\Phi_l}{c} = D\Phi_g + DU_g \frac{\Phi_g}{c}$$

horizontal velocity continuous

Viscous linear stability problem II

boundary conditions on interface(s)

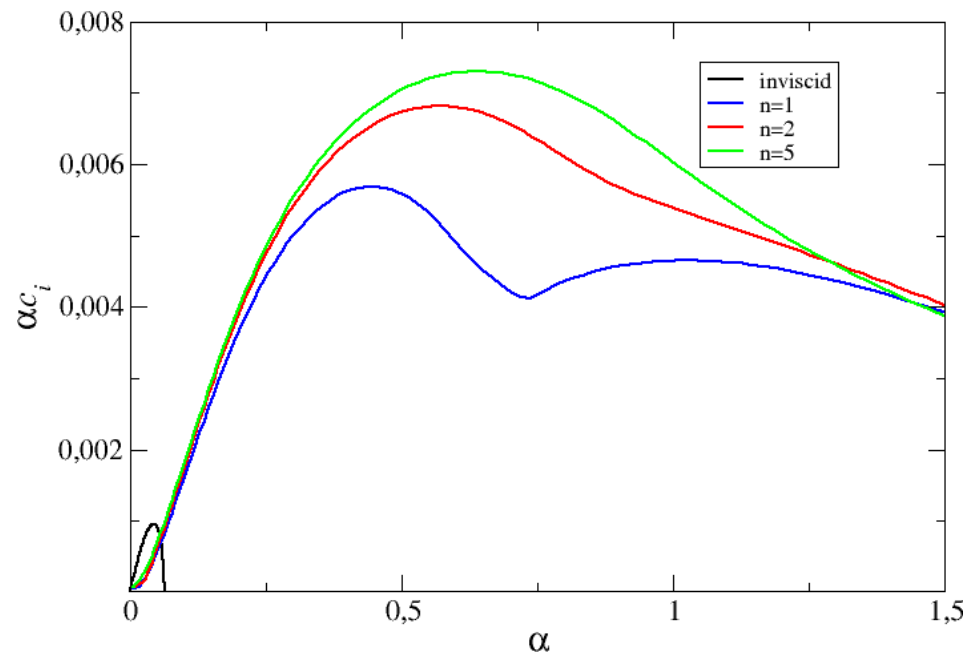
$$m(D^2 + \alpha^2 + \frac{1}{c}D^2U_g)\Phi_g = (D^2 + \alpha^2 + \frac{1}{c}D^2U_l)\Phi_l \quad \text{continuity of tangential stress}$$

$$-\frac{\alpha^2}{cWe_g}\Phi_g = -\frac{1}{r}(cD\Phi_l + \Phi_l DU_l) - \frac{r}{m i \alpha Re_g}(D^3 - 3\alpha^2 D)\Phi_l$$

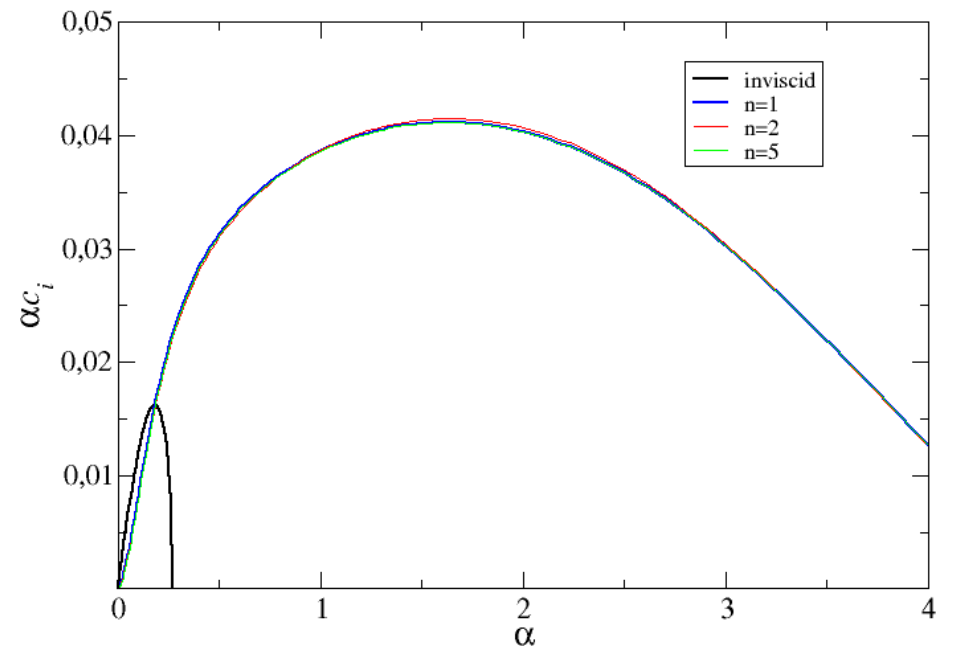
$$+ cD\Phi_g + \Phi_g DU_g + \frac{1}{i \alpha Re_g}(D^3 - 3\alpha^2 D)\Phi_g \quad \text{continuity of normal stress}$$

viscous case

$We_g=10, Re_g=500, r=0.001, m=0.02$

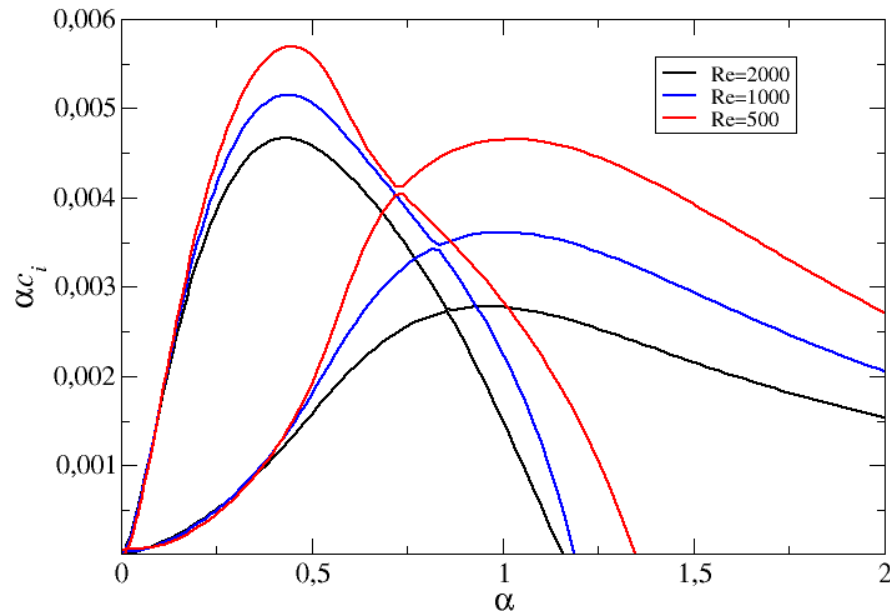


$Re_g=1000, We_g=200, r=0.02, m=0.025$

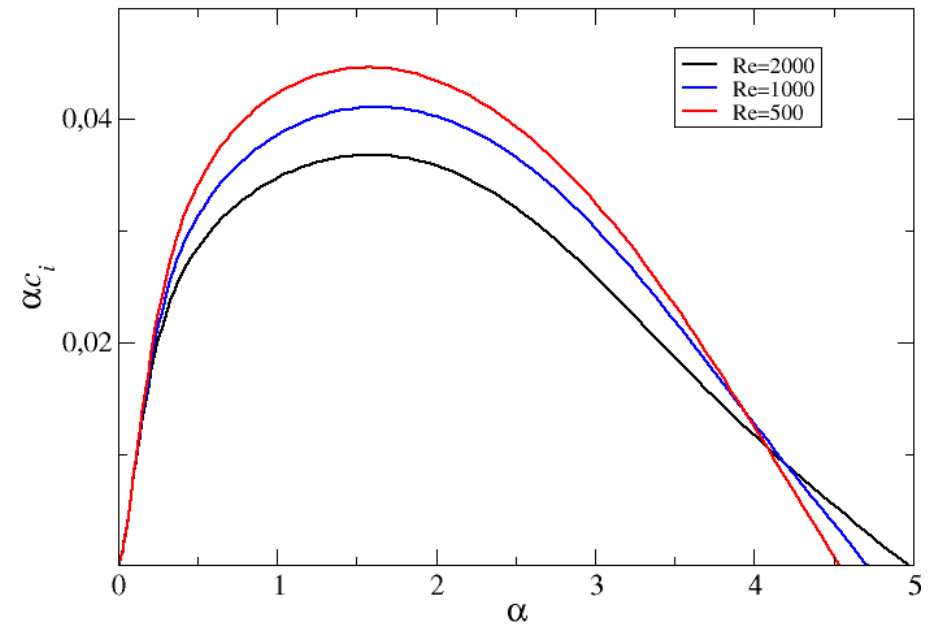


Reynolds number influence

$We_g=10, n=1, r=0.001, m=0.02$



$We_g=200, n=1, r=0.02, m=0.025$

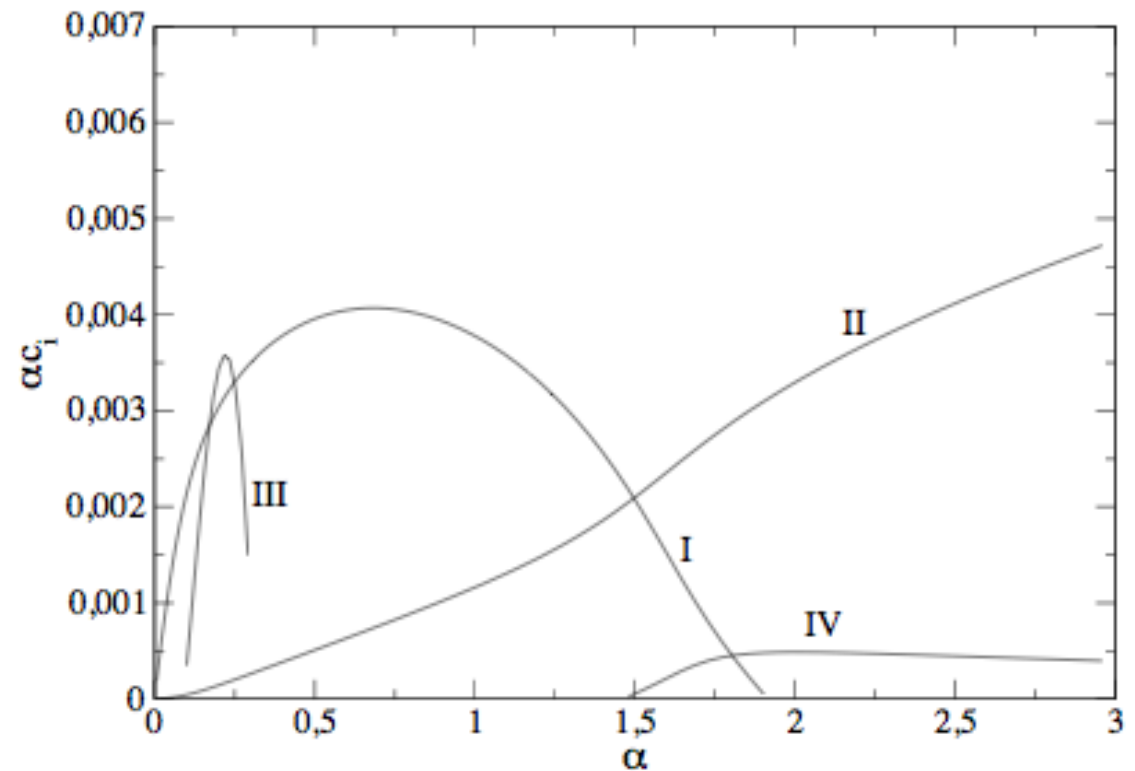


Air-water case $Re = 3 \times 10^4$ $We = \text{infinity}$

I : connects to inviscid KH at **very high Re**

II : H-mode (**zero Re** mode)

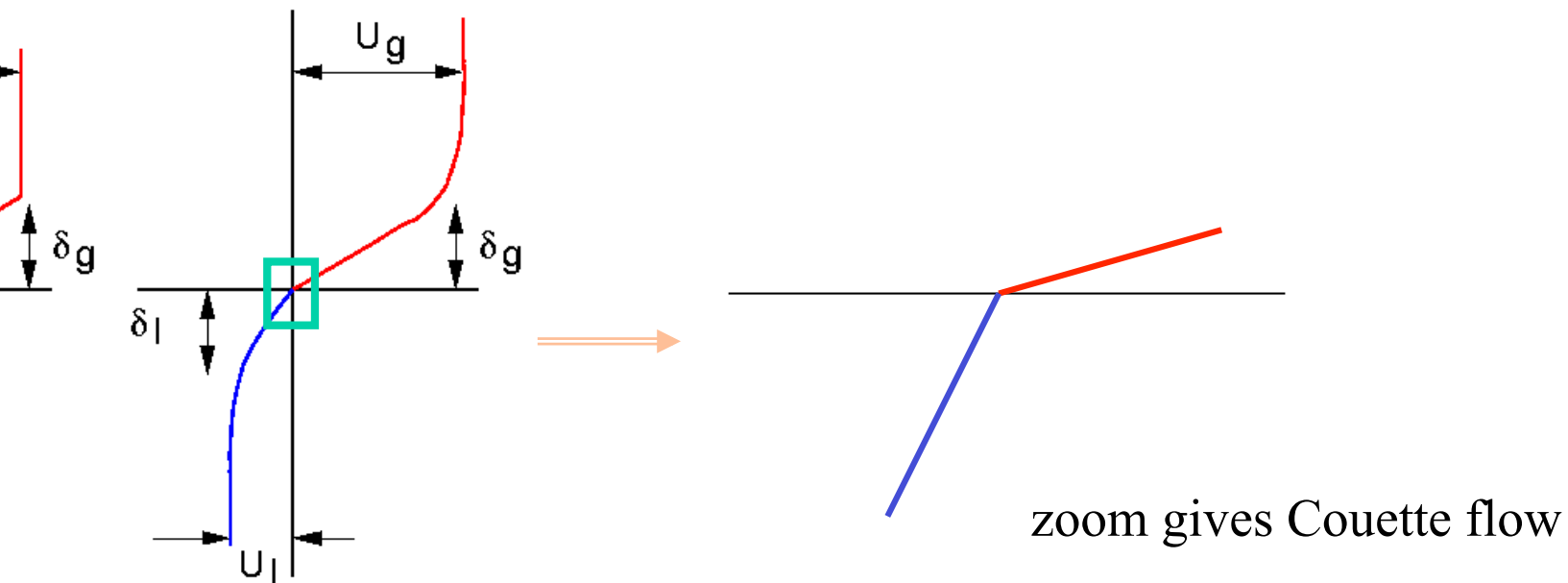
III : similar to Tollmien-Schlichting



It is the interaction of the H mode (mode I) and the inviscid mode (mode II) that explains the difference between the Orr-Sommerfeld and inviscid results.

What is the new **H mode** ?

- named after Hooper and Boyd (1982) and Hinch (1984).
- a mode at $Re=0$
- zoom in on vicinity of the interface



- The H mode is an instability of Couette flow at zero Re. The scaling of the H mode can be explained as follows:
- the only time scale in the shear layer is

$$1 / \omega_g = \delta_g / U_g$$

thus the only length scale is

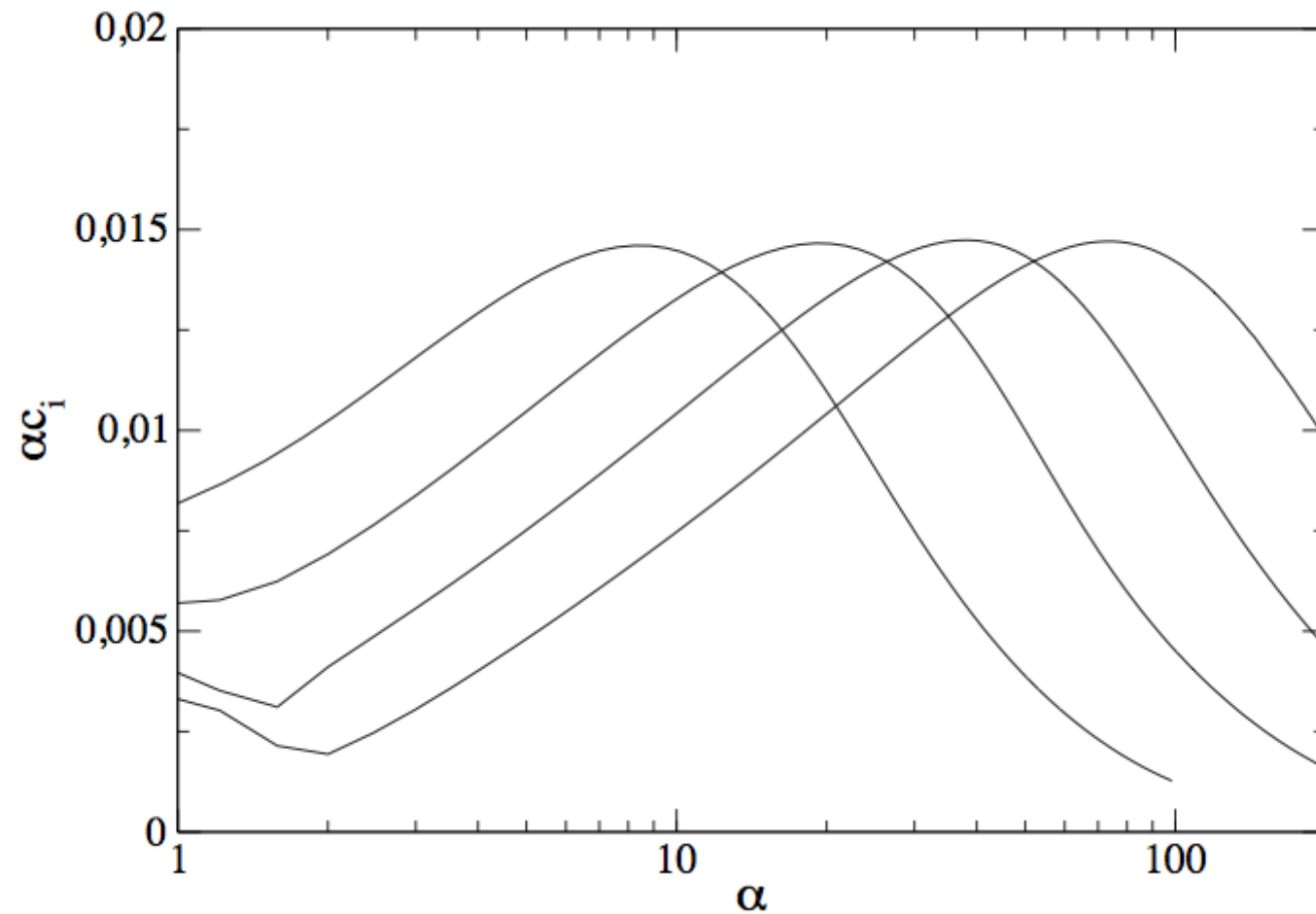
$$l = \sqrt{\frac{\nu_g}{\omega_g}} = \frac{\delta_g}{\sqrt{\text{Re}_g}}$$

implies that the (dimensionless) most unstable wavenumber grows like

$$\sqrt{\text{Re}_g}$$

H-mode branch is shifted in log diagram when Re is increased

Air-water case $Re = 2 \cdot 10^3, 10^4, 4 \cdot 10^4, 1.2 \cdot 10^5$, $We = \text{infinity}$



Numerical solutions of the Orr-Sommerfeld equations in the range of the experiments show that dimensional wavelength decreases like

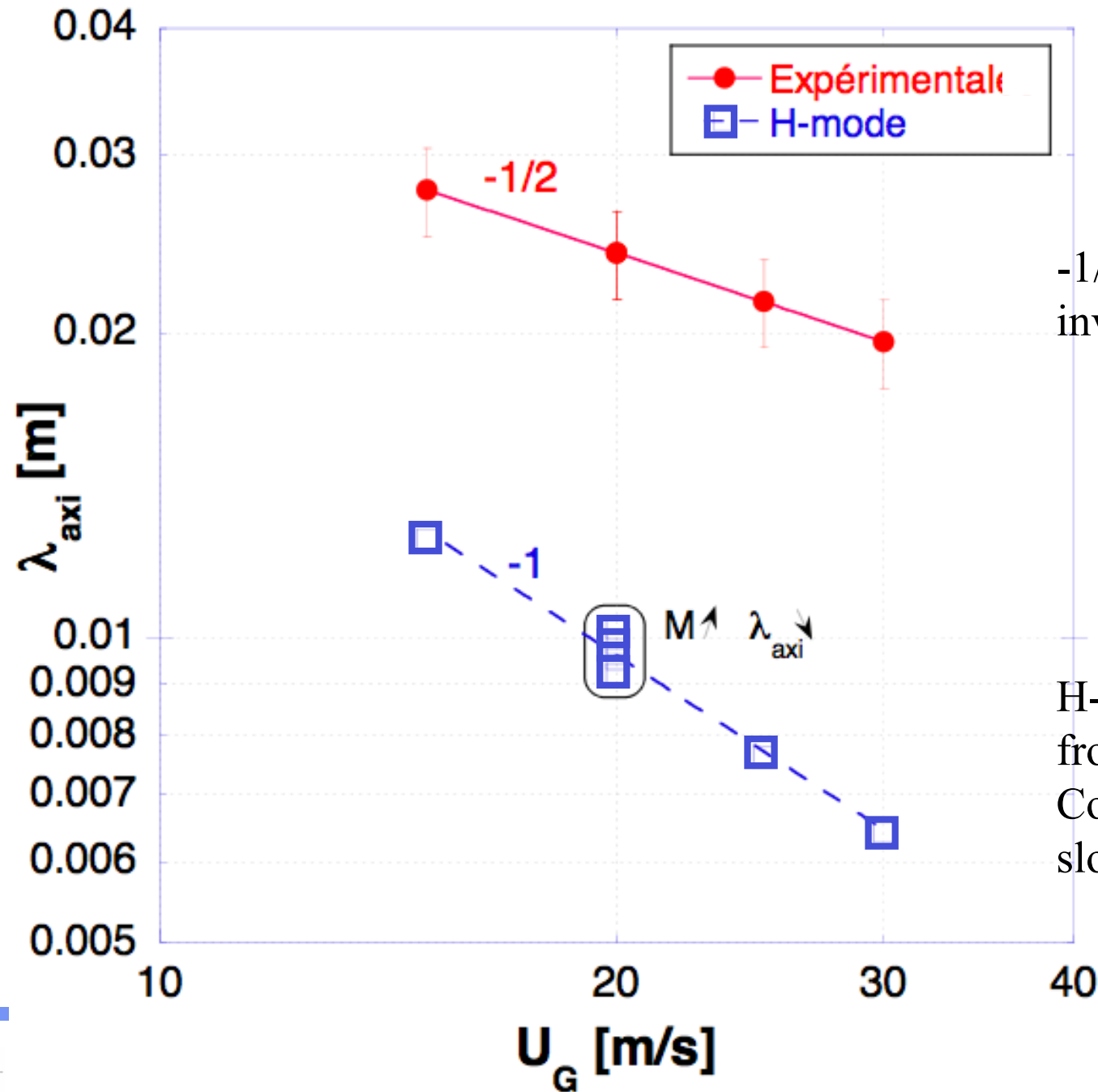
$$\lambda \approx U_g^{-1}$$

But experimental results show rather

$$\lambda \approx U_g^{-1/2}$$

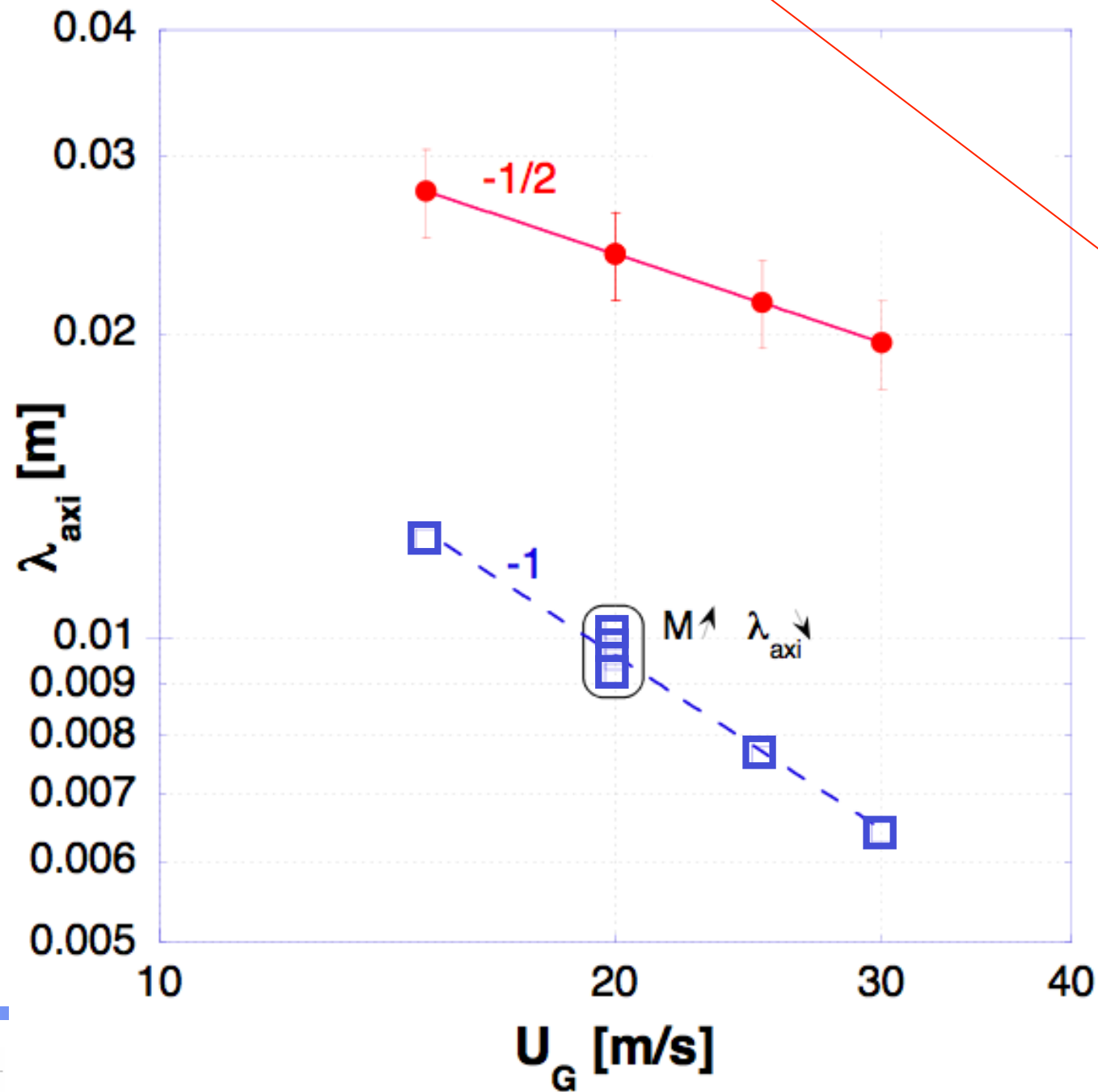
which is the result expected for the inviscid mode !

But the theory fails....



-1/2 slope from
inviscid theory.

H-mode obtained
from Orr-Sommerfeld
Computations. -1
slope !!!



Inviscid theory
also « fails ».
Its prediction
are here ..
but with the
correct scaling.

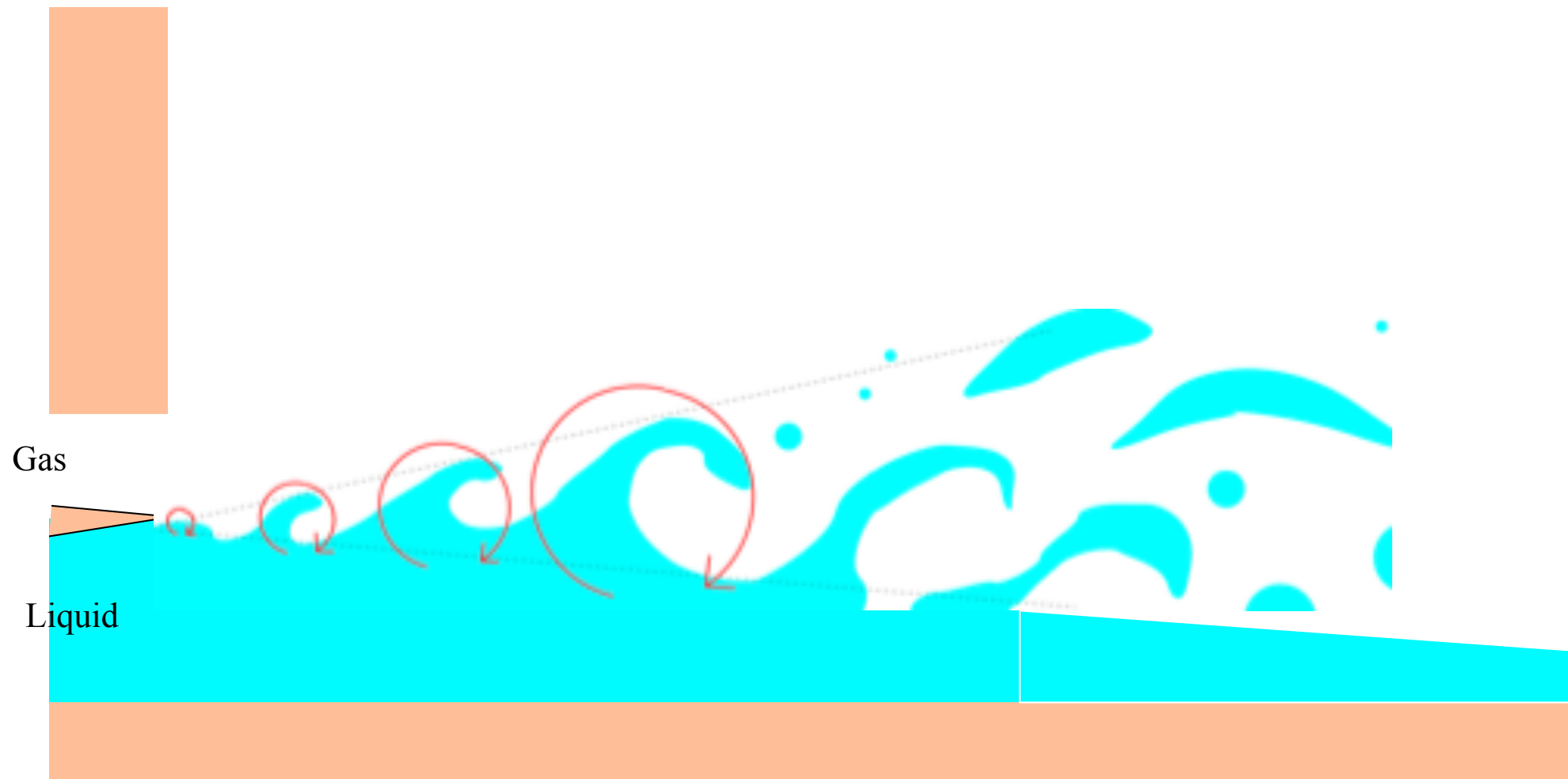
We are convinced that the real world is viscous ... but the experiment can be interpreted only using inviscid scaling theories !

Simple explanations:

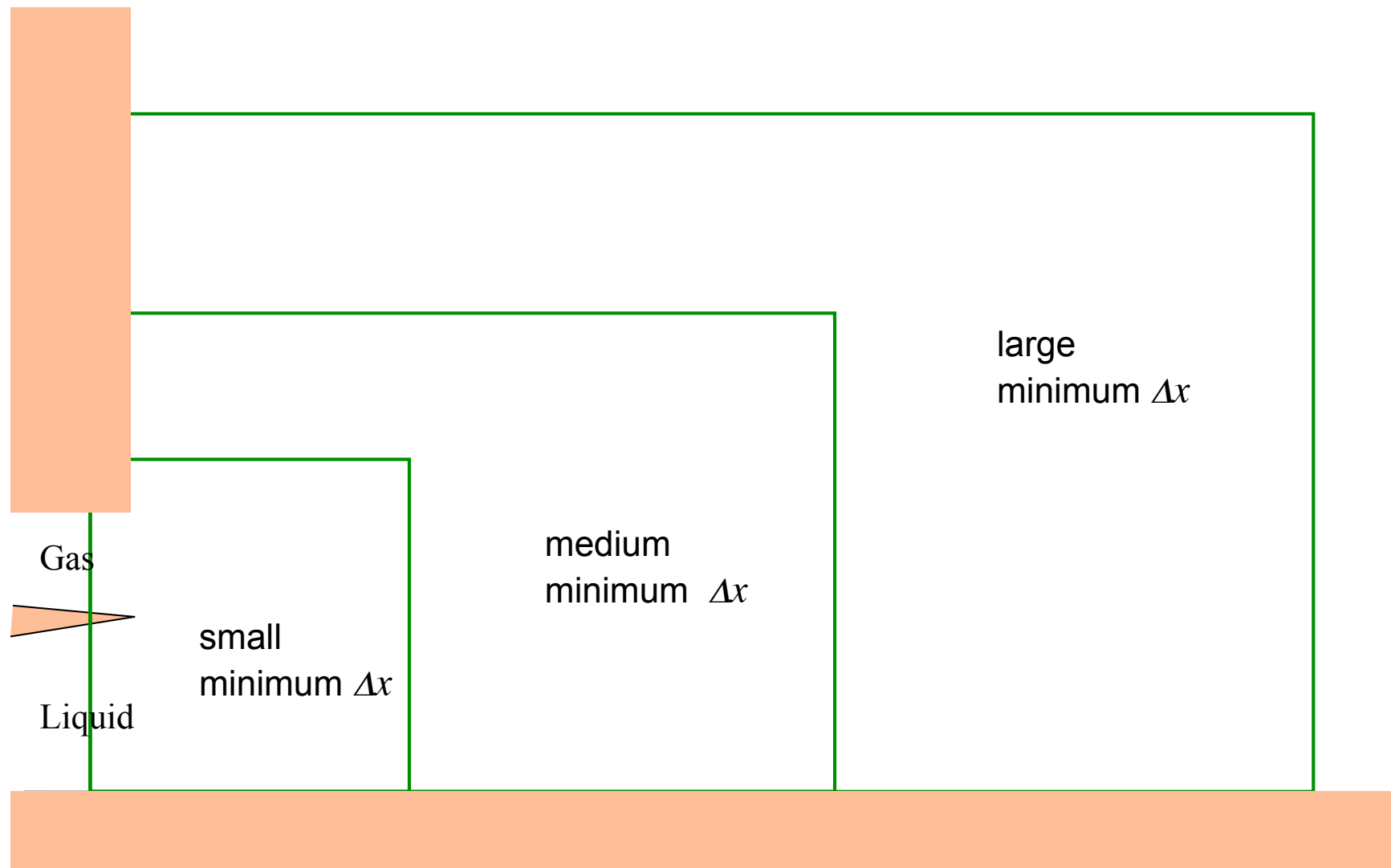
- the experiment is wrong (after all, it took « them » ten years to fix the errors in the initial measurements 😊).
- the Gaster transformation does not apply (but would this change the scaling?)

Gerris will at least allow us to verify the experiment

Back to the « Grenoble » 2D setup.



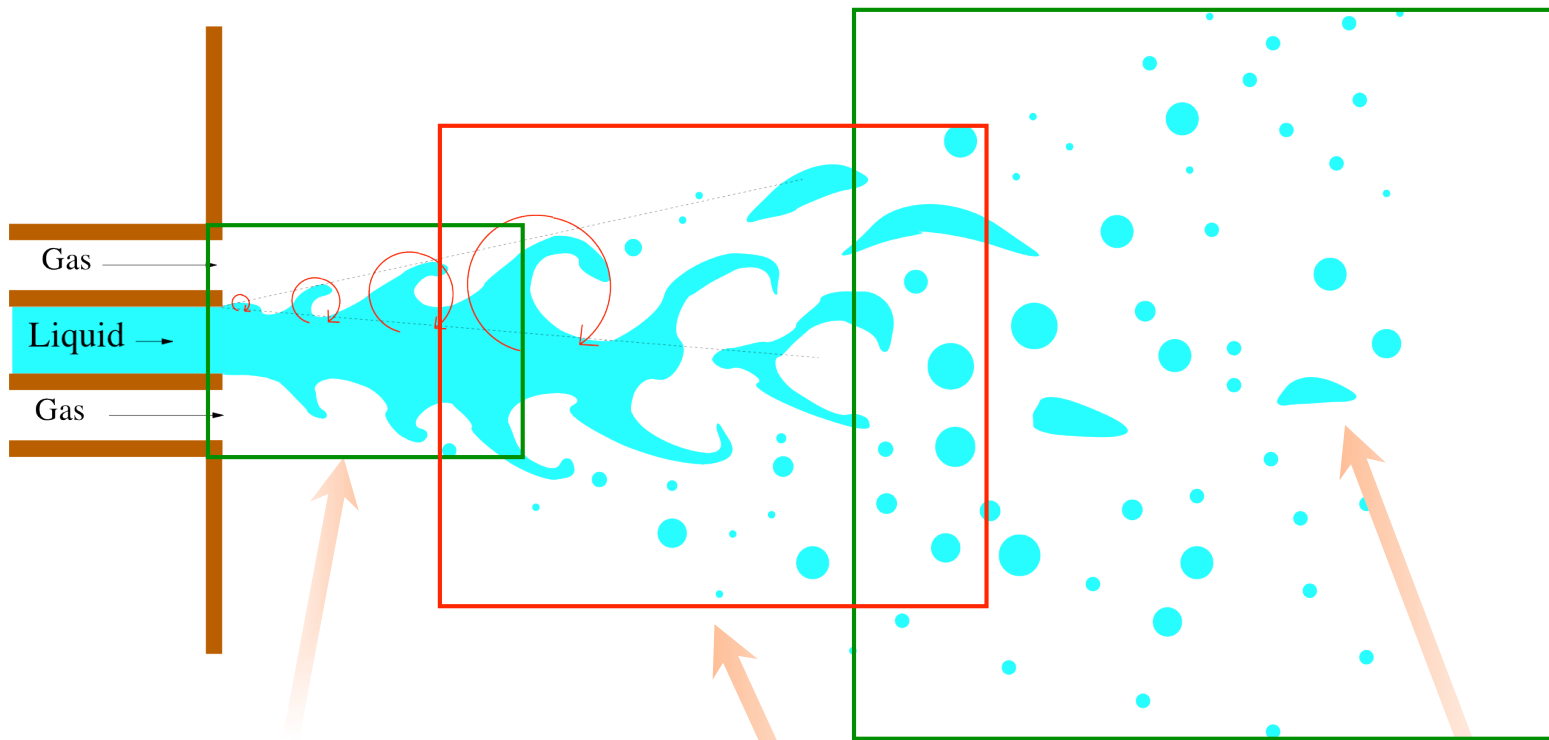
Elementary **multiscale treatment**: Navier-Stokes with variable minimum grid size according to a subdivision of the computational domain.



More refined multiscale modelling ?

E and Enquist (Comm. Math. Sci, 2003) introduce the following typology :

- Type A problems : problems that require a localised effort to capture explicitly the smallest scales. Typically a boundary layer.
- Type B problems: large regions containing a homogeneous distributions of smaller scales for which an effective larger-scale model must be found. Typically the derivation of Navier-Stokes from kinetic theory, or an averaged multiphase-flow model.

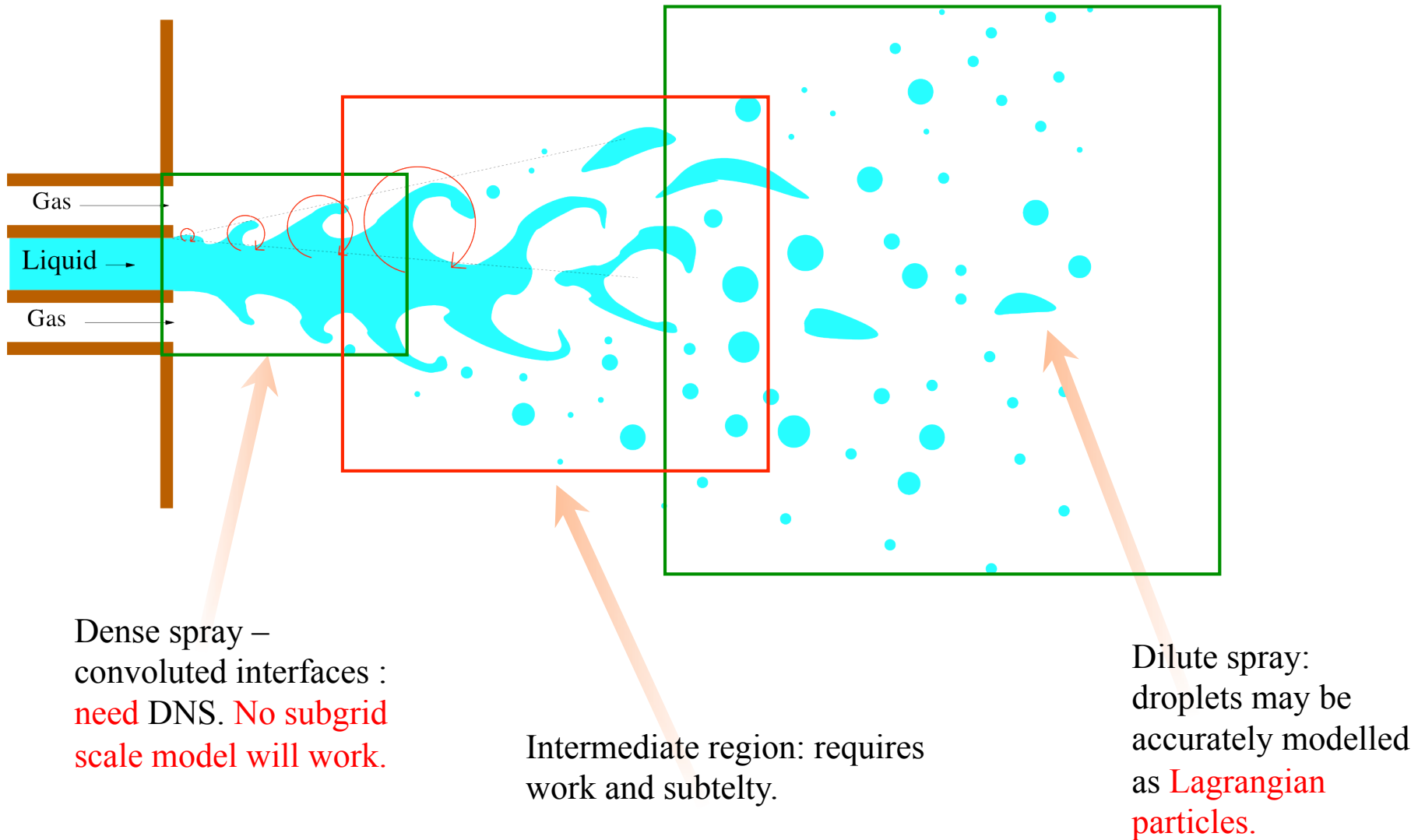


Dense spray –
convoluted interfaces :
Type A region.

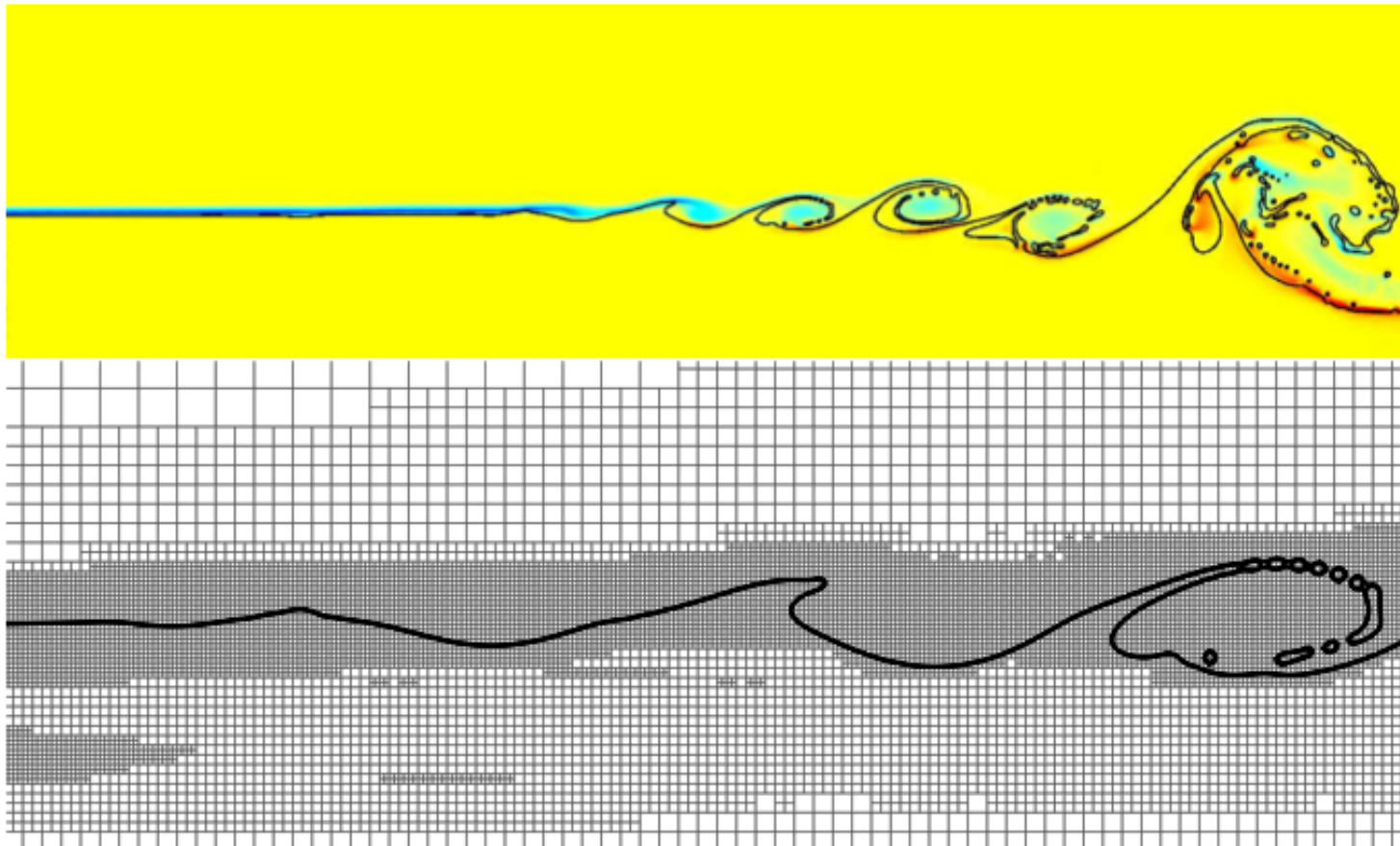
Intermediate region: Type A
regions with progressive
coarsening downstream.

Type B region:
dilute spray.

Simulation methodology



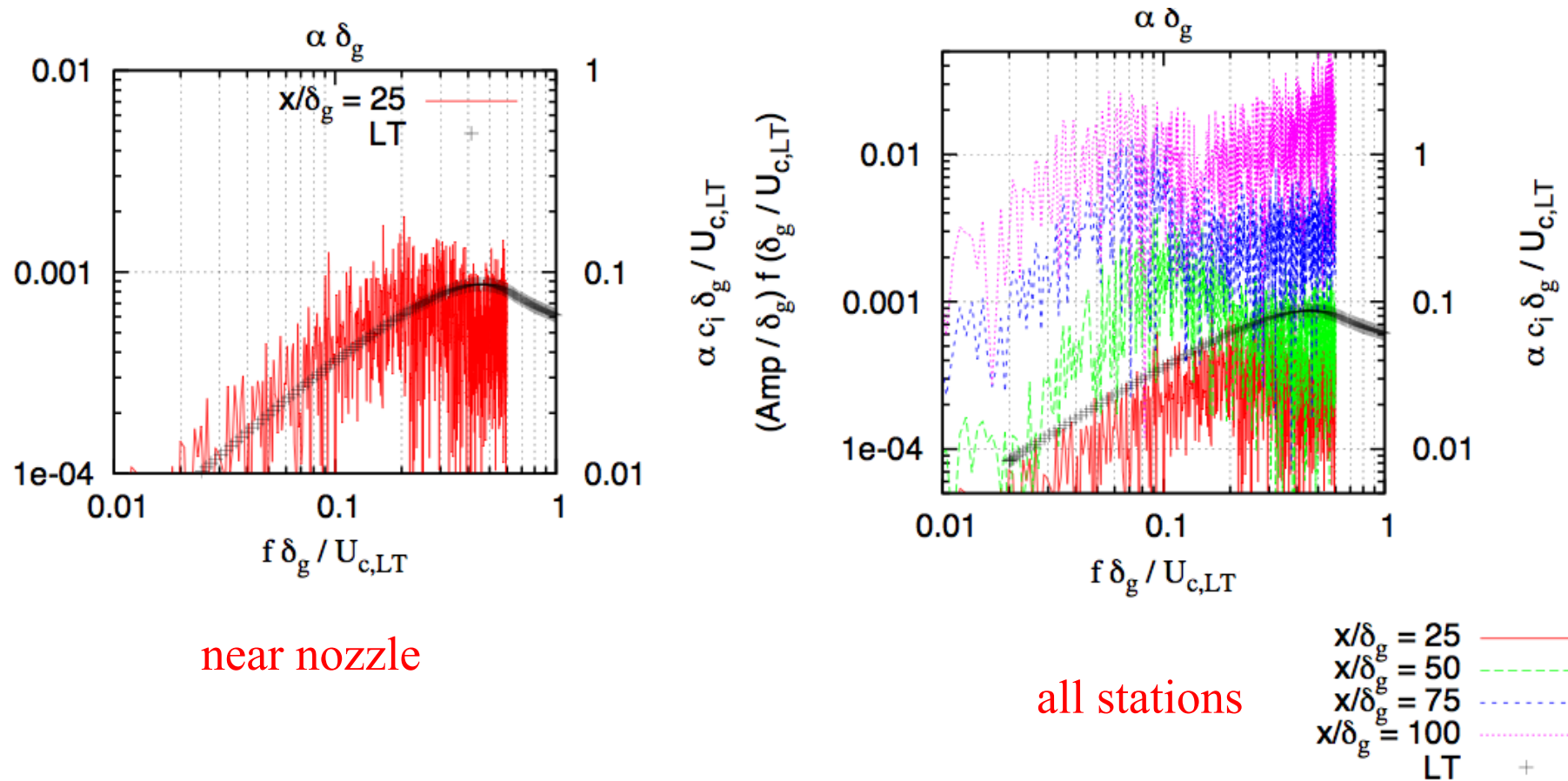
Turn to full, spatially developing DNS



m	r	Re_l^*	Re_q^*	We_l^*	We_q^*	M
0.034	0.200	471	2350	157	133	5.00

Fuster et al. 2009. IJMF

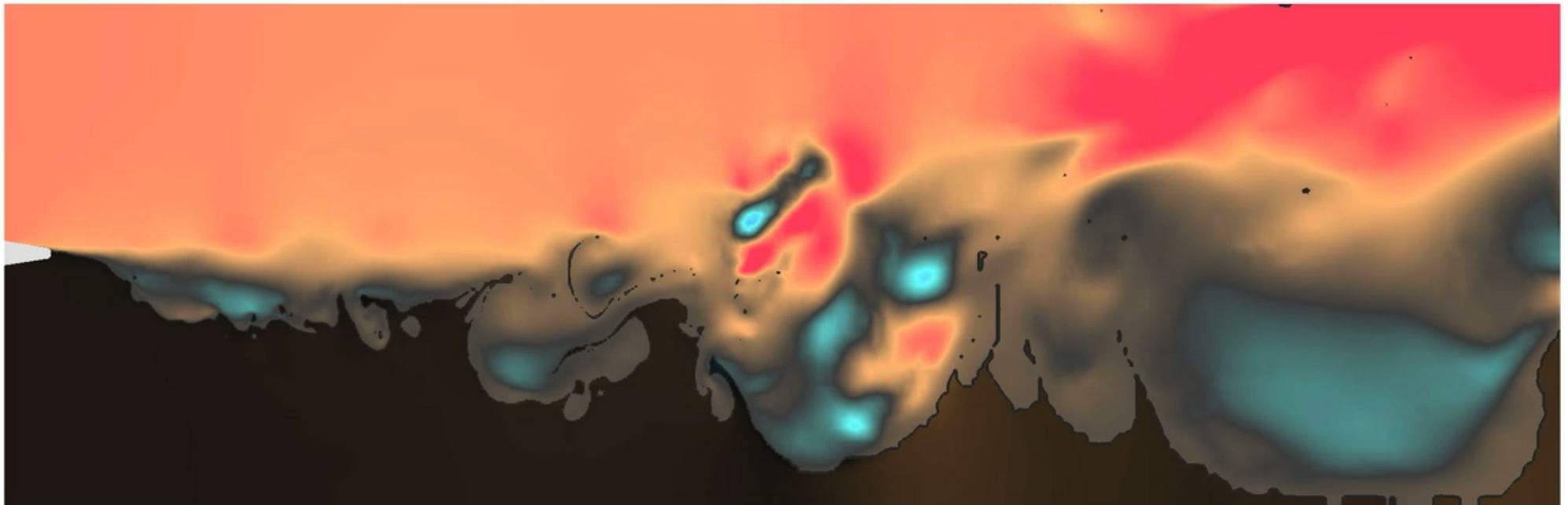
Viscous, Orr-Sommerfeld theory is verified !!



Not the real experimental parameters however (not air-water properties)

Simulation with a separator plate at larger density ratio ($1/r$)

m	r	Re_g	Re_l	We_g	We_l	M
0.017	0,01	2640	290	19	8	2,4



Conclusion

We are not solving the problems that we think we are solving

The End